



UNIVERSITÀ DEGLI STUDI  
DI TRENTO

CUDAM - Centro Universitario per la Difesa  
Idrogeologica dell'Ambiente Montano

HydroloGIS

Environmental

Engineering

# Environmental modeling within the framework of GIS

HydroloGIS  
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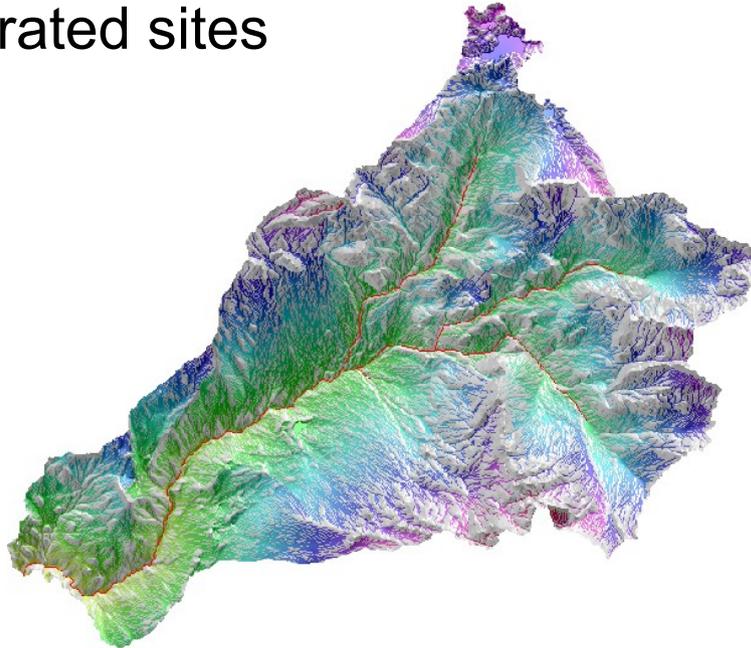
UniTN - CUDAM  
Riccardo Rigon

**Models, models,  
models...**

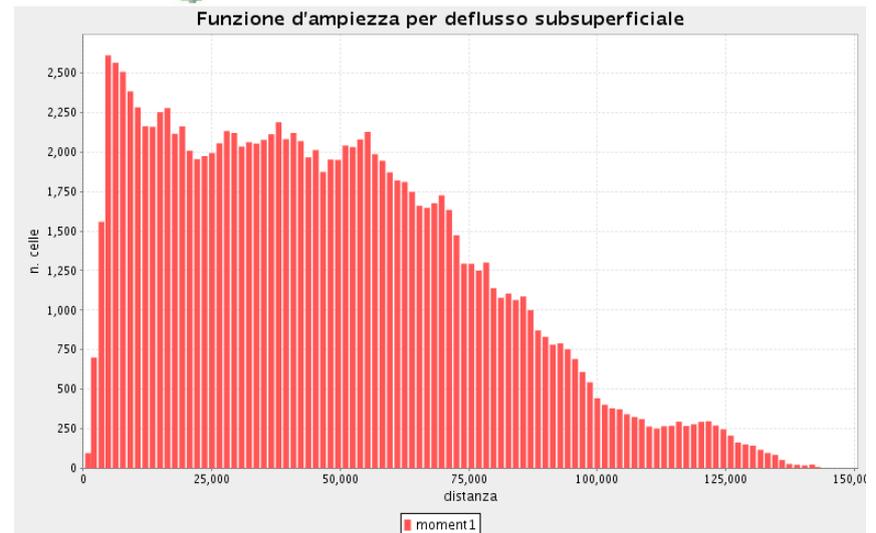
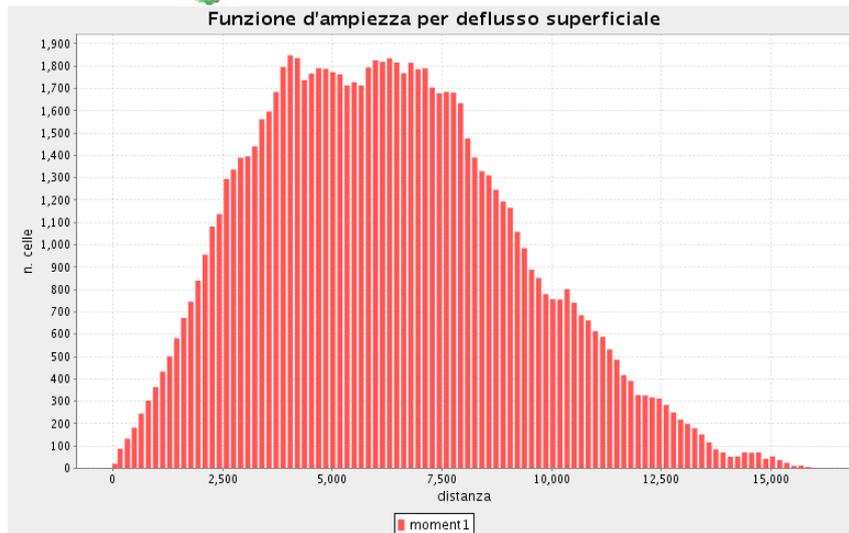
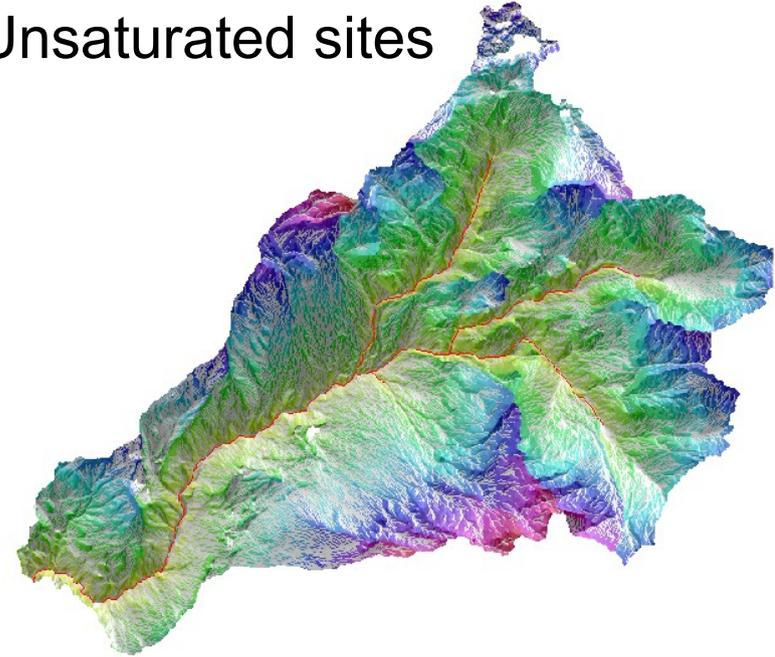
# Models, models, models...

**PEAKFLOW**: semidistributed hydrological model. It works using the GIUH approach and calculates both the **maximum discharge and the duration of the precipitation that maximises the discharge.**

## Saturated sites



## Unsaturated sites



**Peakflow**

input file with the superficial width function:  ...

input file with the subsuperficial width function:  ...

a parameter of IDF curves [m/h^n]:

n parameter of IDF curves:

channel celerity [m/s]:

diffusion [m2/s]:

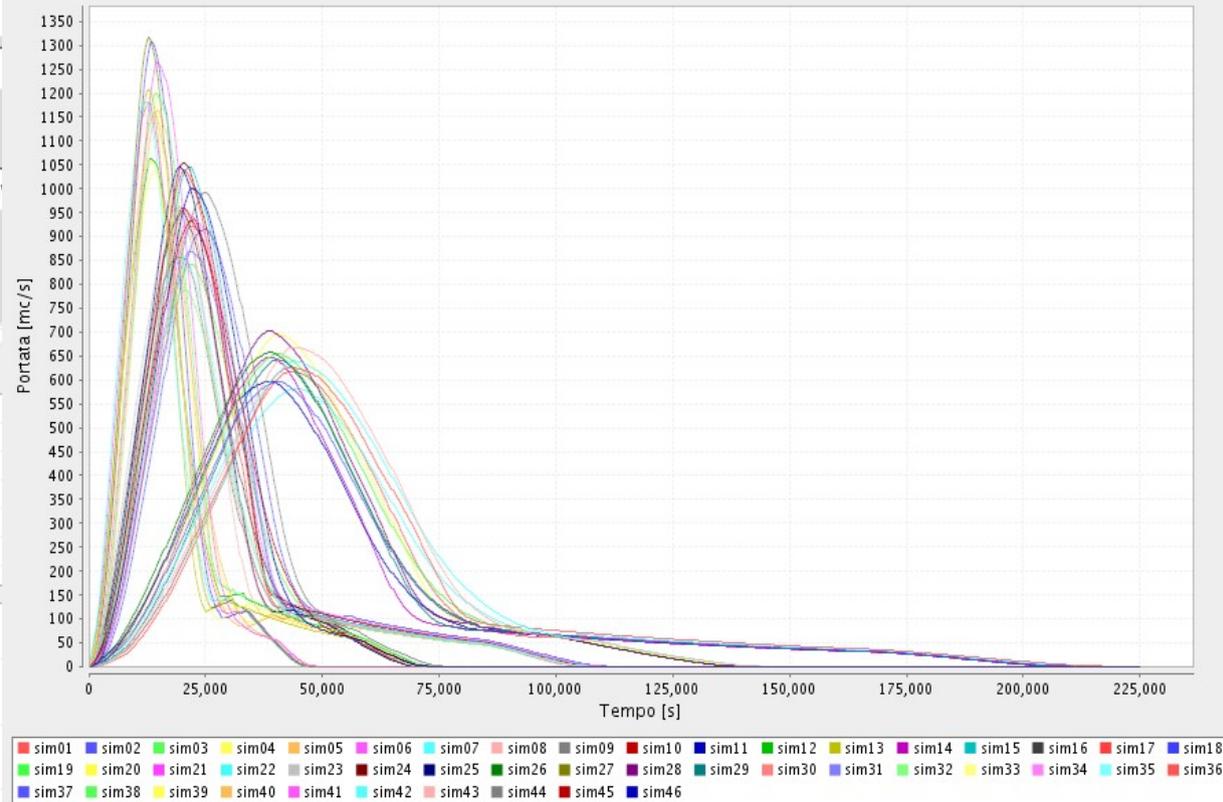
output file timestep [s]:

write an output discharge file

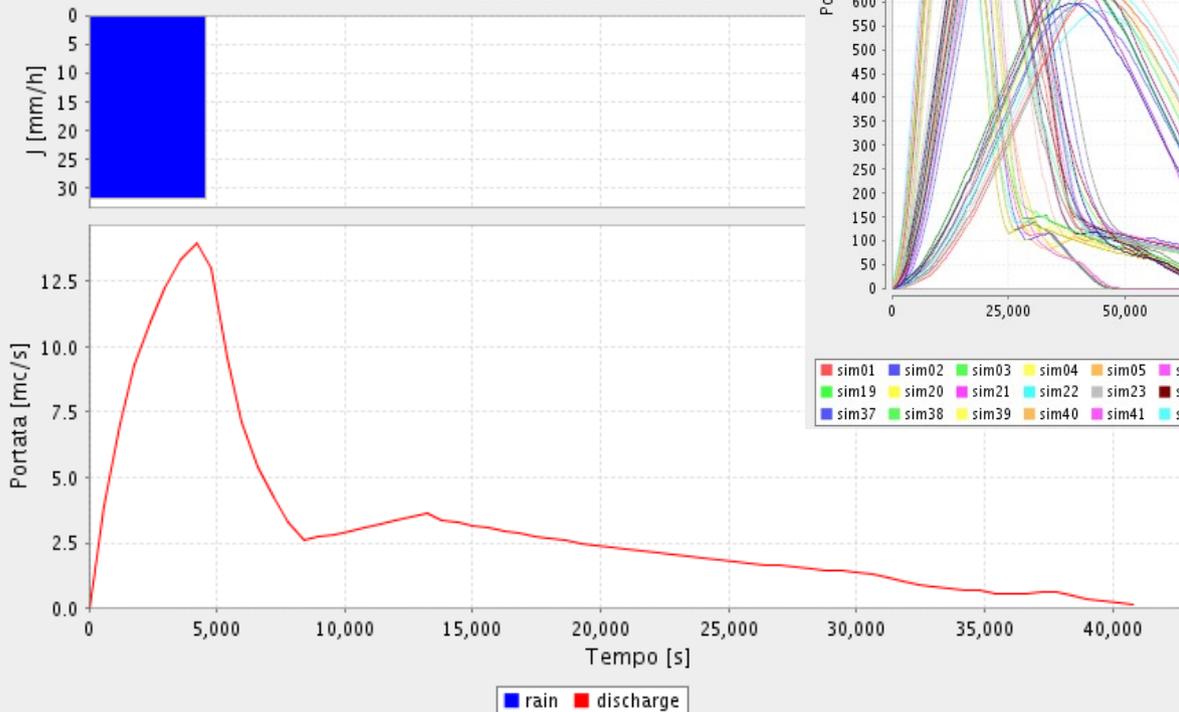
output discharge file:

create the discharge chart

**Portate relative a saturazione del bacino del 50%**



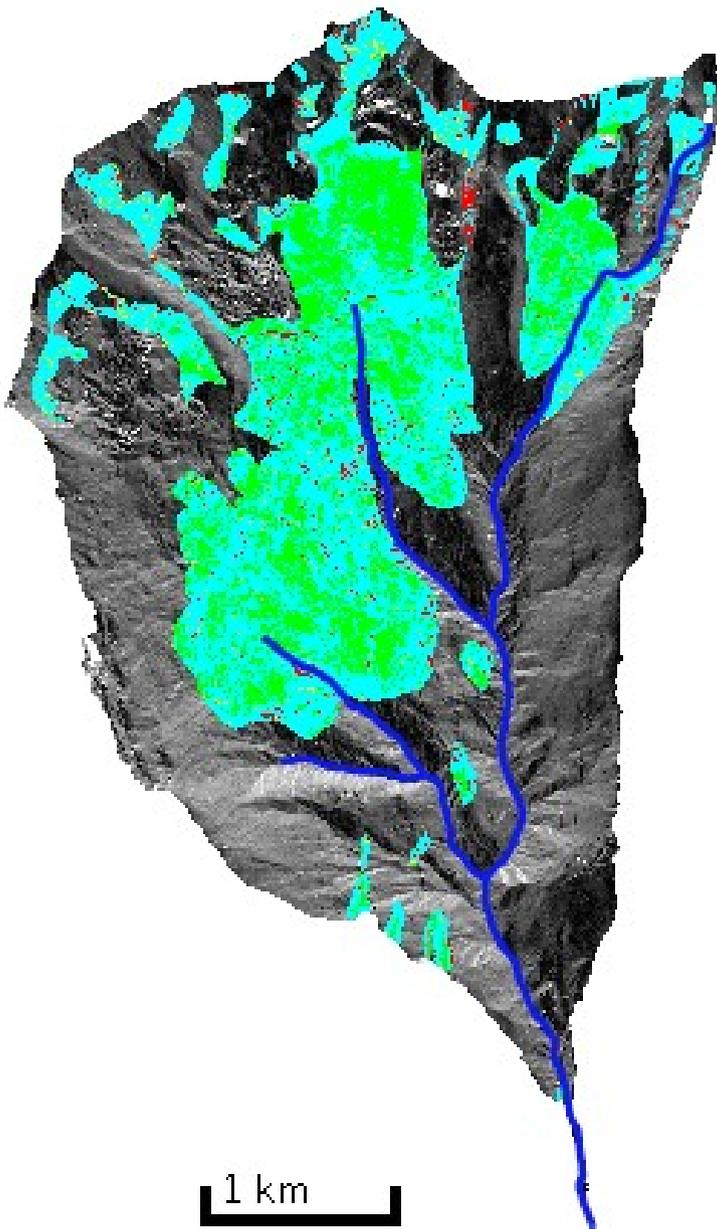
**Portata calcolata**



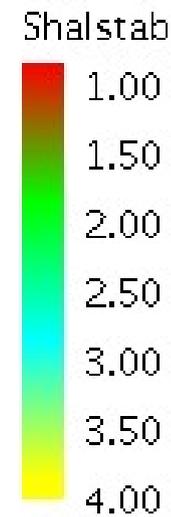
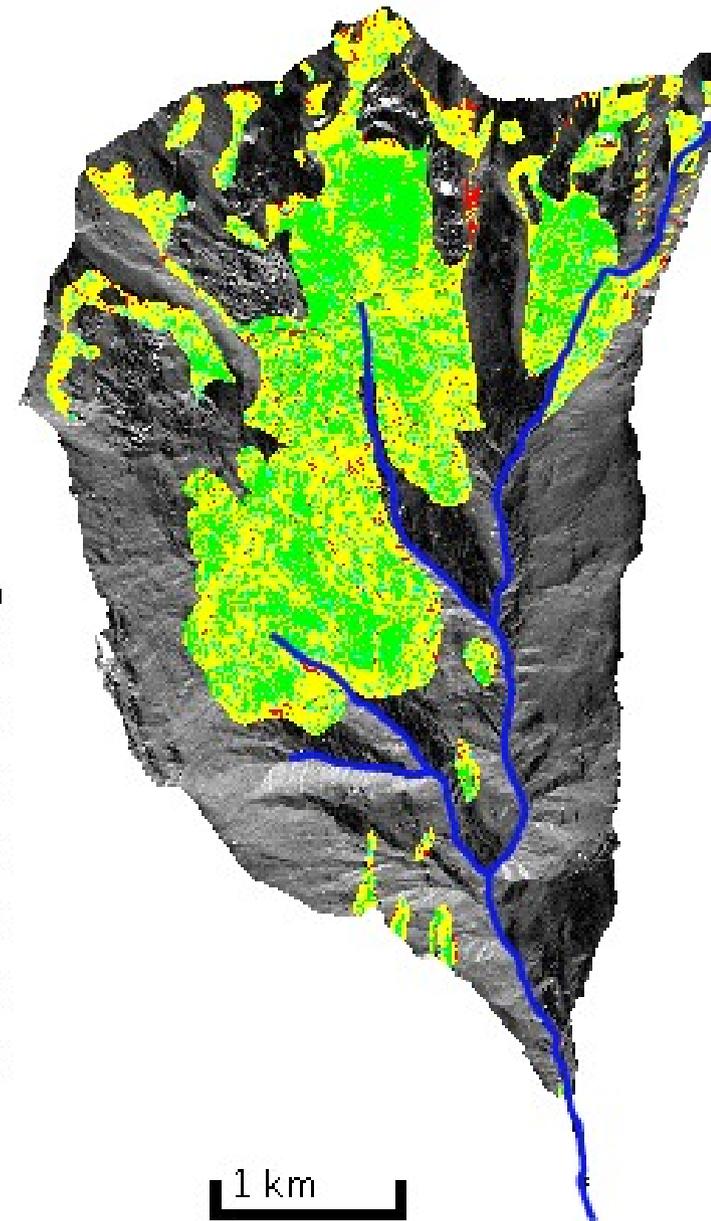
## Models, models, models...

**PEAKFLOW**: semidistributed hydrological model. It works using the GIUH approach and calculates both the **maximum discharge and the duration of the precipitation that maximises the discharge.**

**SHALSTAB**: a version of the shalstab model, which uses a simplified hydrological model and the model of infinite slope to **evaluate a stability coefficient.**



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1	Inc Instabile
2	Inc Stabile
3	Stabile
4	Instabile



# Models, models, models...

**PEAKFLOW**: semidistributed hydrological model. It works using the GIUH approach and calculates both the **maximum discharge and the duration of the precipitation that maximises the discharge.**

**SHALSTAB**: a version of the shalstab model, which uses a simplified hydrological model and the model of infinite slope to **evaluate a stability coefficient.**

**NUOVO ADIGE**: large scale distributed hydrological model including energy and water balance (based on Duffy model implementation in Cuencas).

**It includes the modeling of reservoirs, intakes and human works.**

# Nuovo Adige

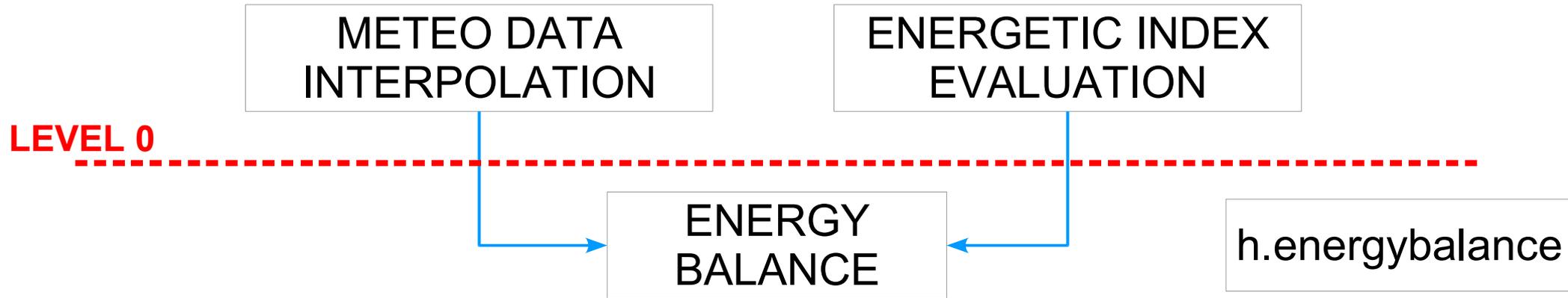
METEO DATA  
INTERPOLATION

ENERGETIC INDEX  
EVALUATION

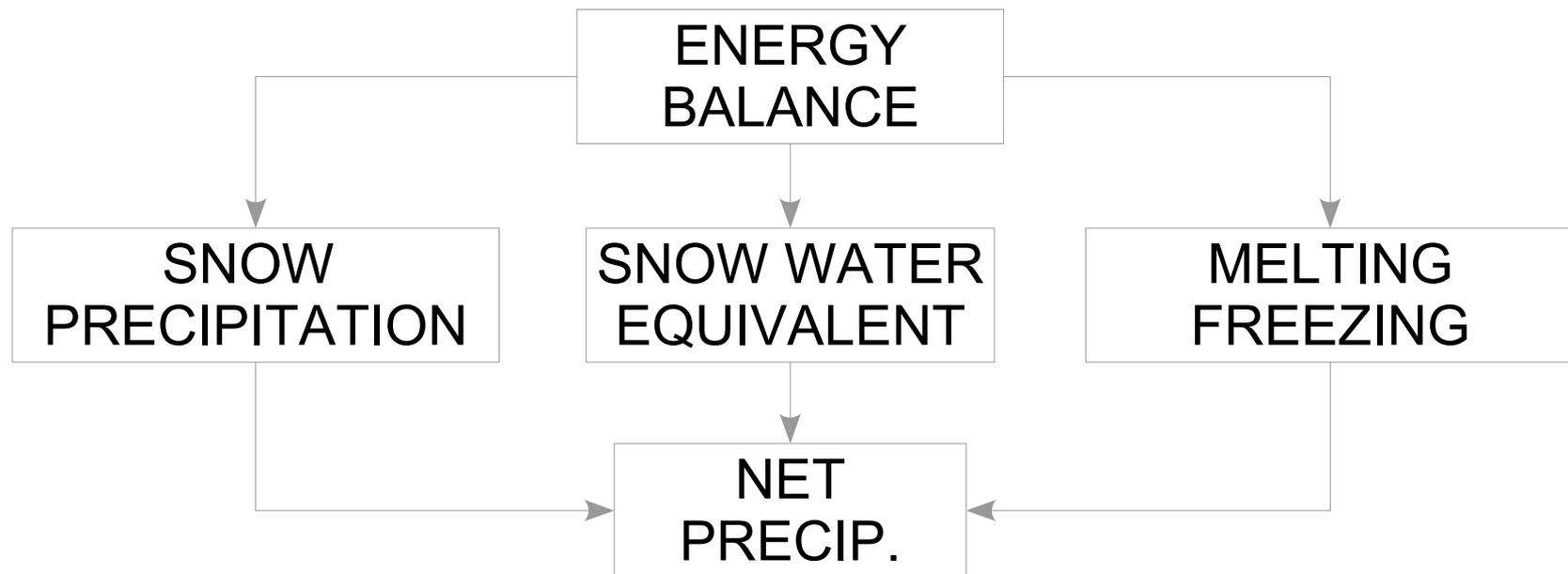
**LEVEL 0**



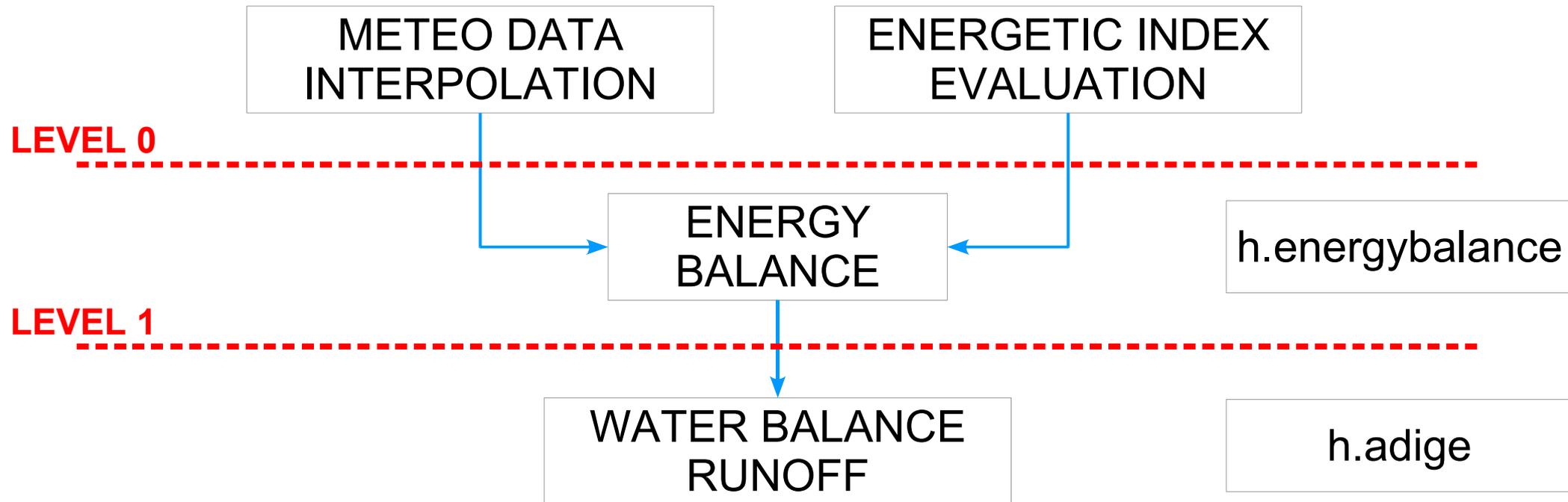
# Nuovo Adige



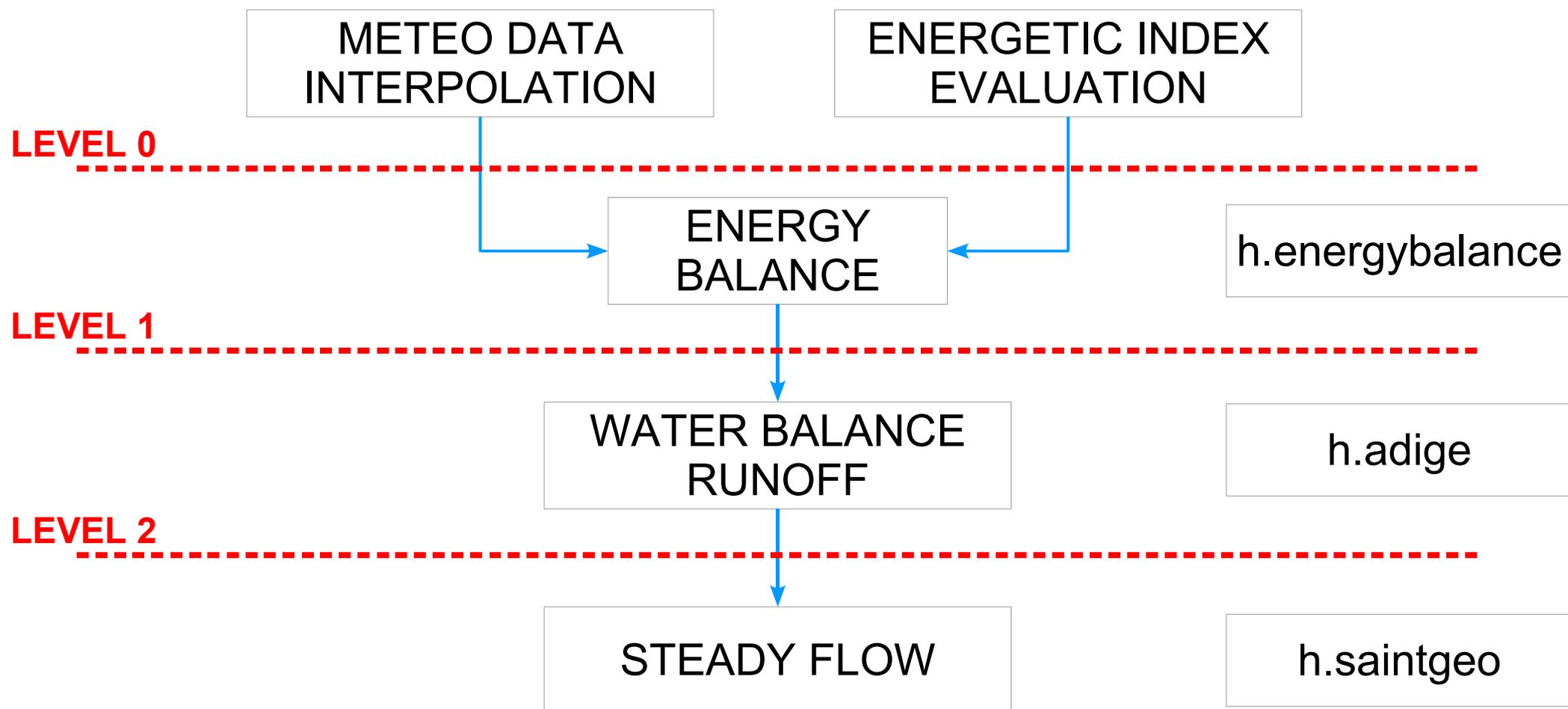
# Nuovo Adige



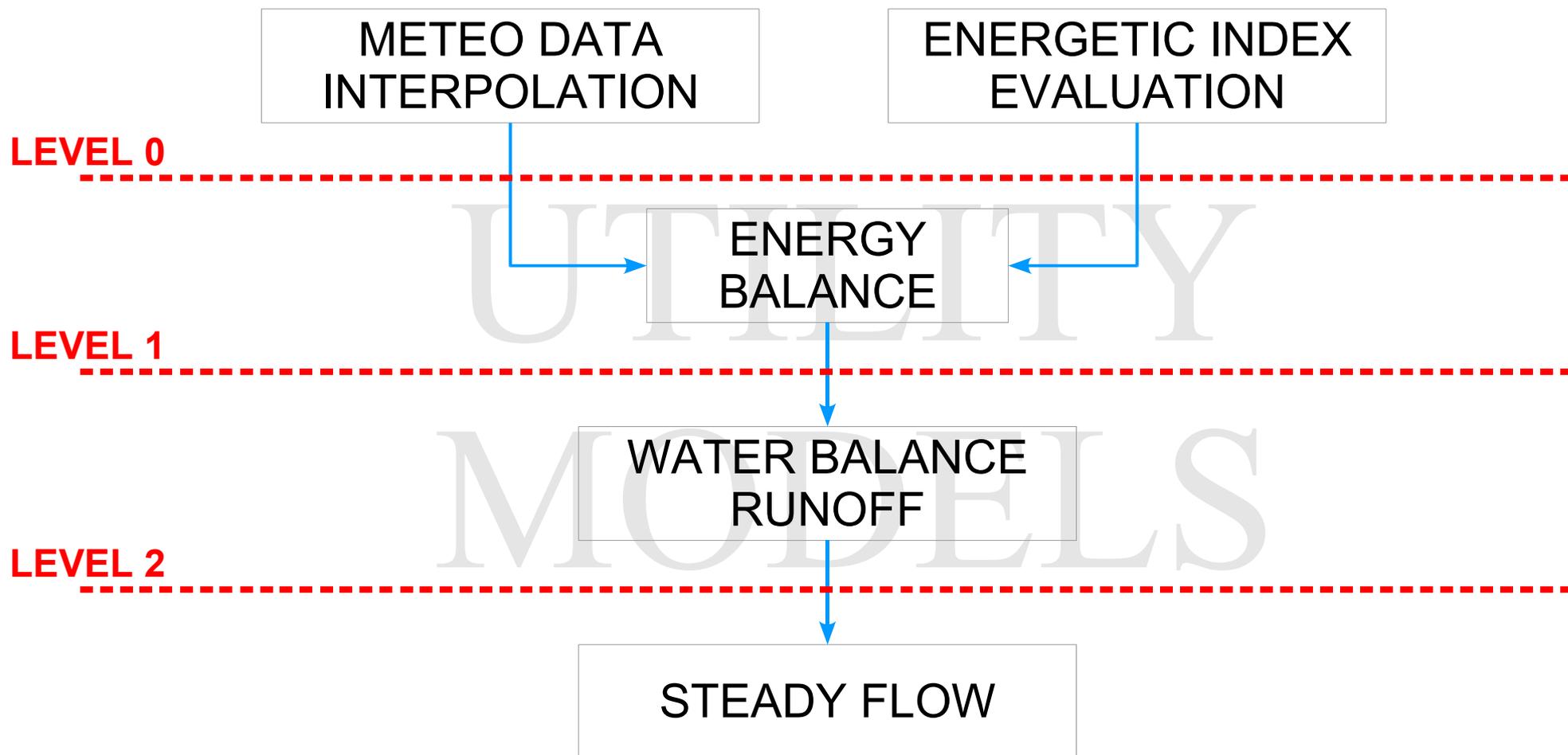
# Nuovo Adige



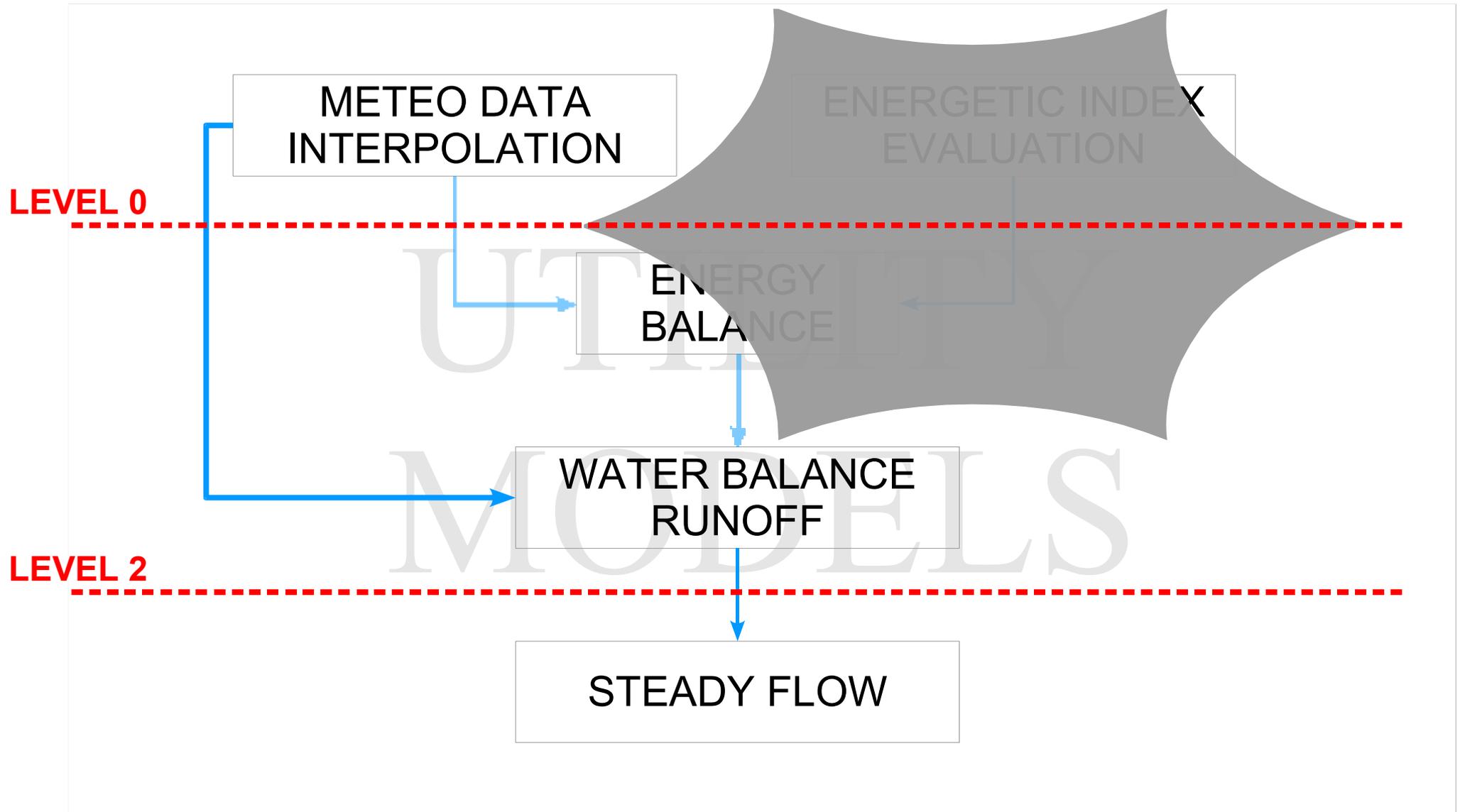
# Nuovo Adige



# Nuovo Adige



# Nuovo Adige



**How is this done?**

# The Horton Machine

## The Horton Machine

**h.peakflow, h.shalstab,  
h.energybalance, h.adige are all  
part of the Horton Machine**

## The Horton Machine

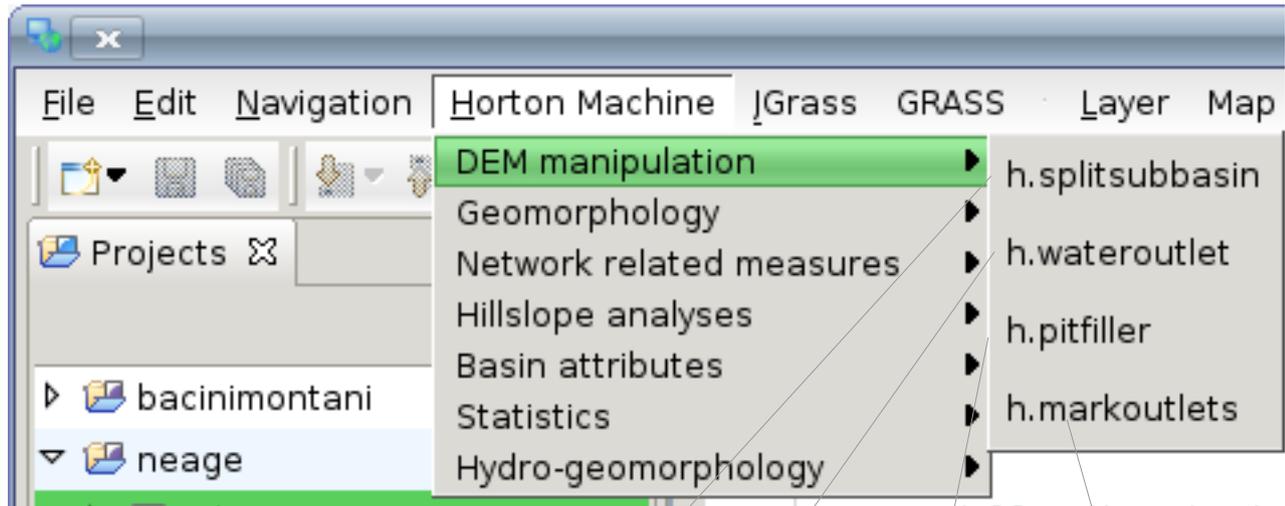
# **h.peakflow, h.shalstab, h.energybalance, h.adige are all part of the Horton Machine**

- suite of tools to process digital data of the terrain
- developed at Department of Civil and Environmental Engineering of the University of Trento – Riccardo Rigon
- initially written in C and released under GPL
- recently ported to java inside the FOSS GIS JGrass and released under LGPL

# HortonMachine:

The commands are divided in 7 categories:

- DEM manipulation



Given the Strahler number of the channel network, the subbasins up to a selected order are labeled

Generates a watershed basin mask from a drainage direction map and a set of coordinates

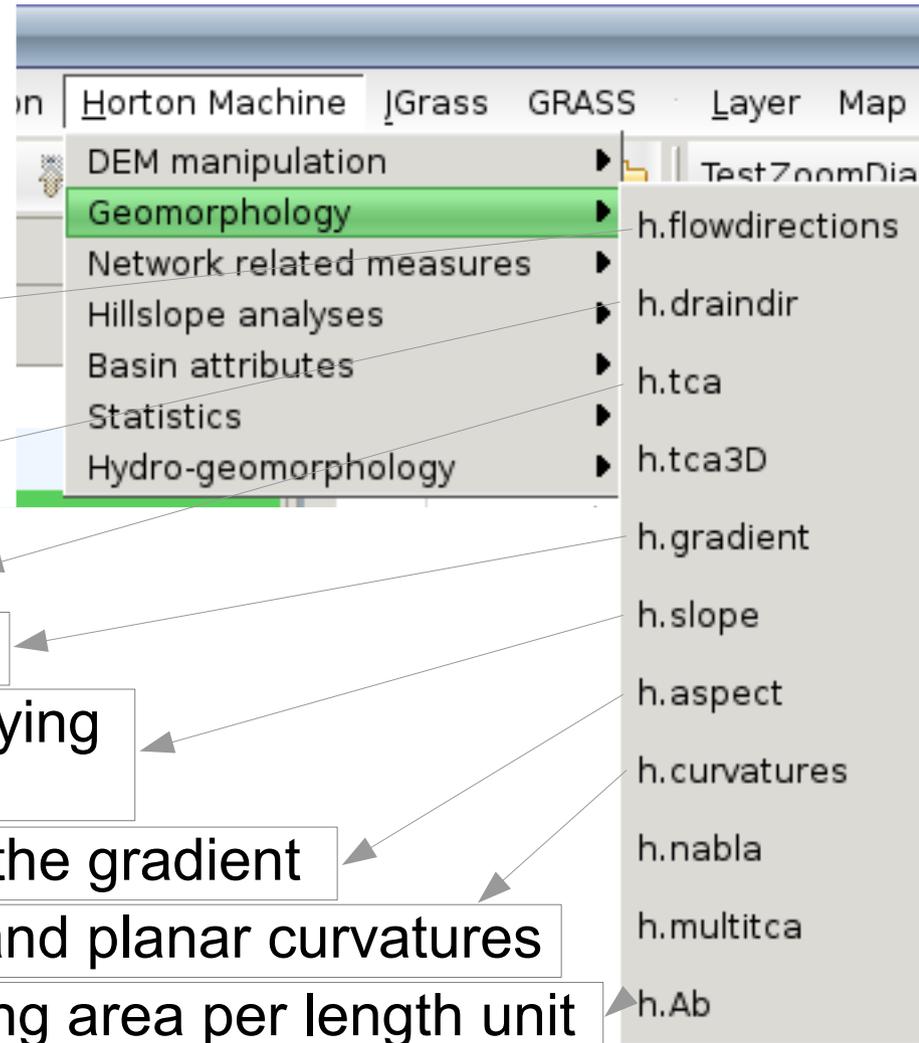
It fills the depression points contained in a DEM so that the drainage directions are defined in each point

"marks" the basin outlets

# HortonMachine:

The commands are divided in 7 categories:

- DEM manipulation
- Geomorphology



drainage directions with the method of the maximal steepest descent slope

drainage directions minimizing the deviation from the real flow

upslope catchment area

module of the gradient vector

slope in every site by employing the drainage directions

inclination angle of the gradient

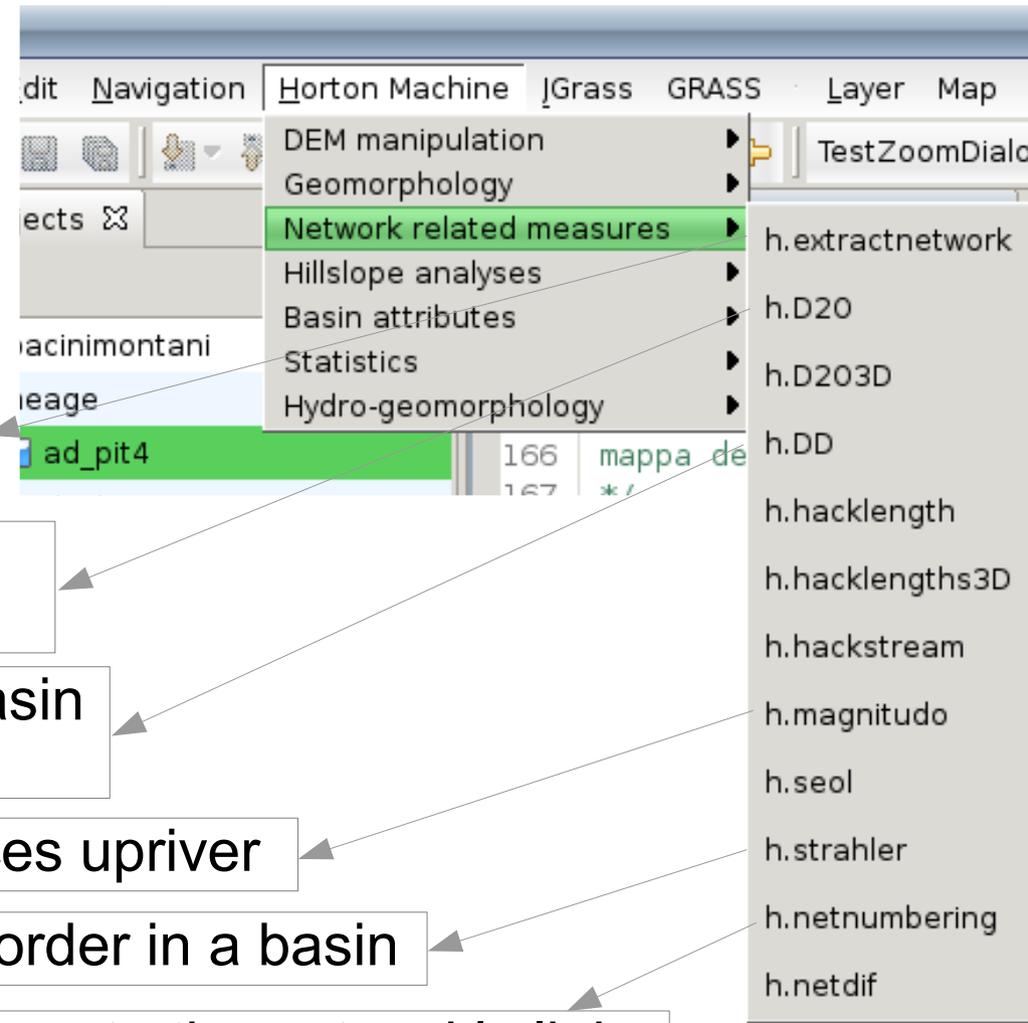
longitudinal, normal and planar curvatures

draining area per length unit

# HortonMachine:

The commands are divided in 7 categories:

- DEM manipulation
- Geomorphology
- Network related measures



extracts the channel network from the drainage directions

distance of each pixel from the outlet, measured along the drainage directions

drainage density function for the basin upstream of each pixel

number of sources upriver

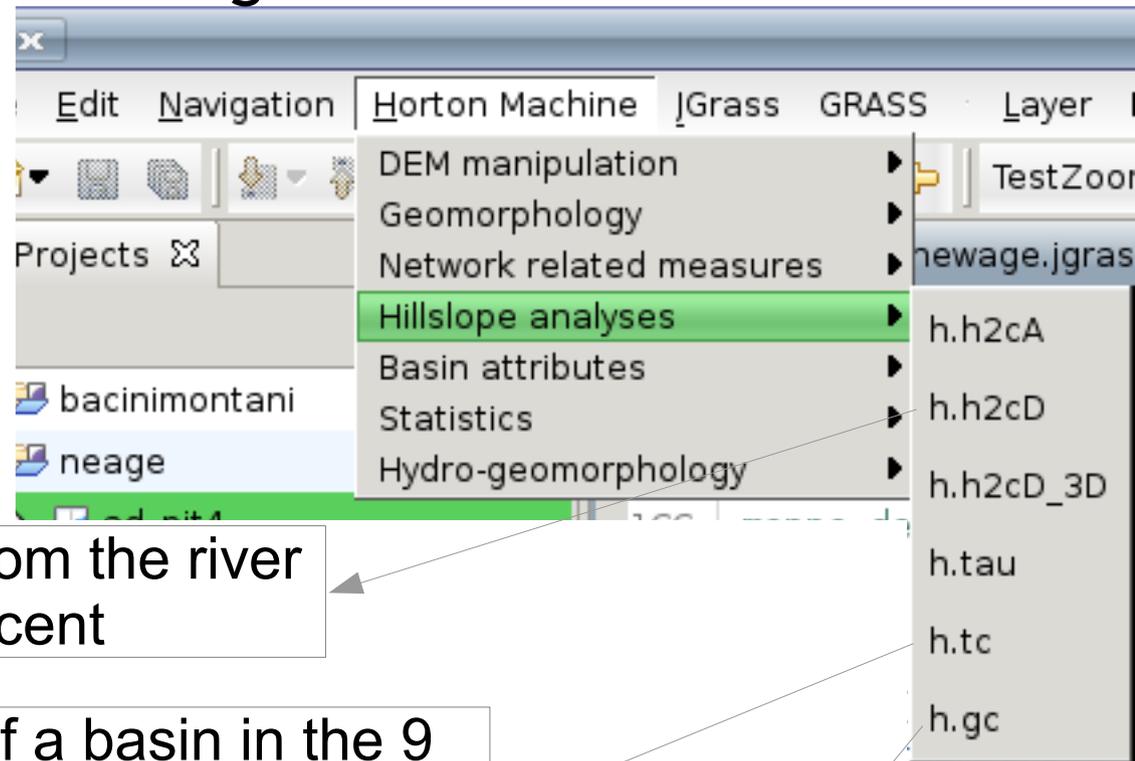
Strahler order in a basin

assign numbers to the network's links

# HortonMachine:

The commands are divided in 7 categories:

- DEM manipulation
- Geomorphology
- Network related measures
- Hillslope analyses



for each hillslope pixel its distance from the river networks, following the steepest descent

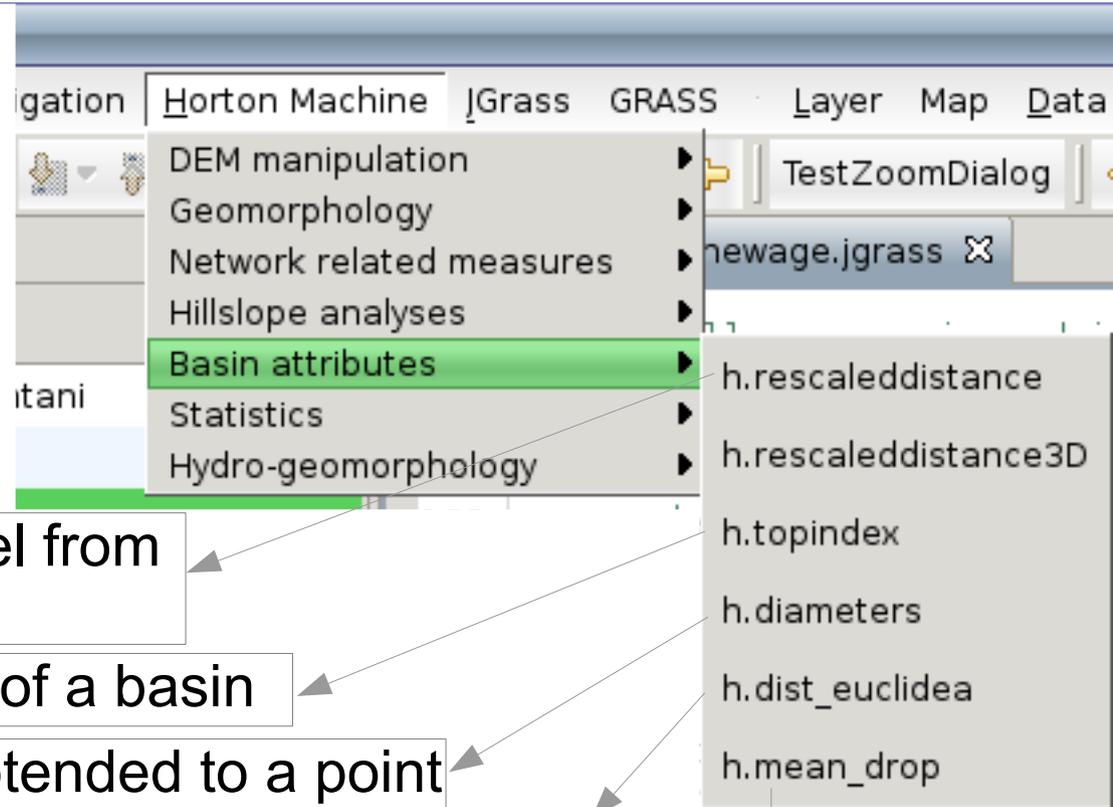
subdivides the sites of a basin in the 9 topographic classes identified by the longitudinal and transversal curvatures

subdivides the sites of a basin in 11 topographic classes (9 from h.tc)

# HortonMachine:

The commands are divided in 7 categories:

- DEM manipulation
- Geomorphology
- Network related measures
- Hillslope analyses
- Basin attributes



rescaled distance of each pixel from the outlet

topographic index of a basin

diameter of the basin subtended to a point

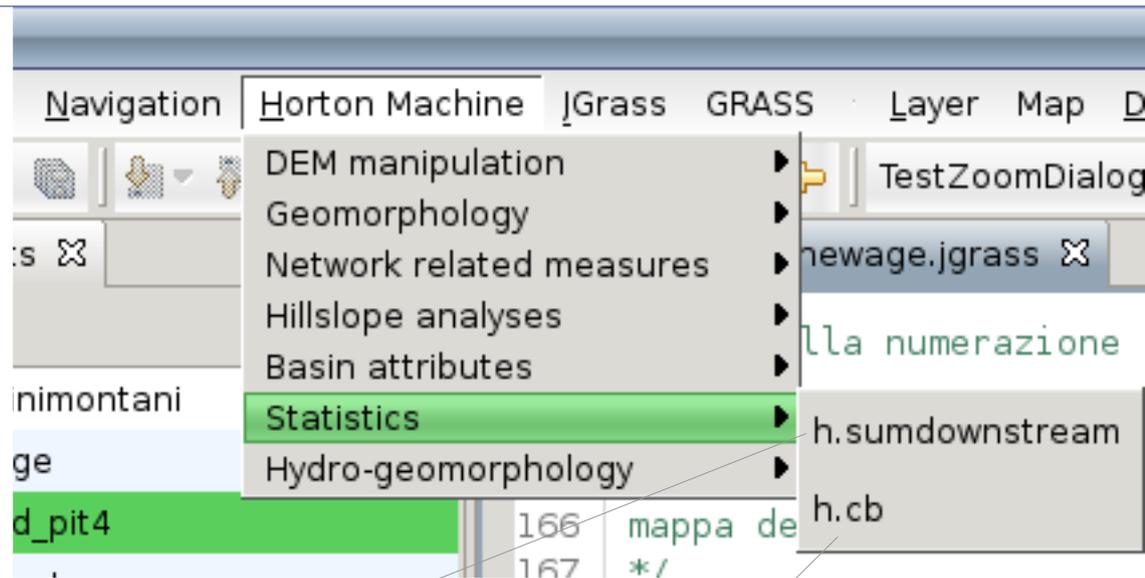
euclidean distance of each pixel from the outlet of the bigger basin which contains it

main moments of inertia of each subnet of a channel net

# HortonMachine:

The commands are divided in 7 categories:

- DEM manipulation
- Geomorphology
- Network related measures
- Hillslope analyses
- Basin attributes
- Statistics



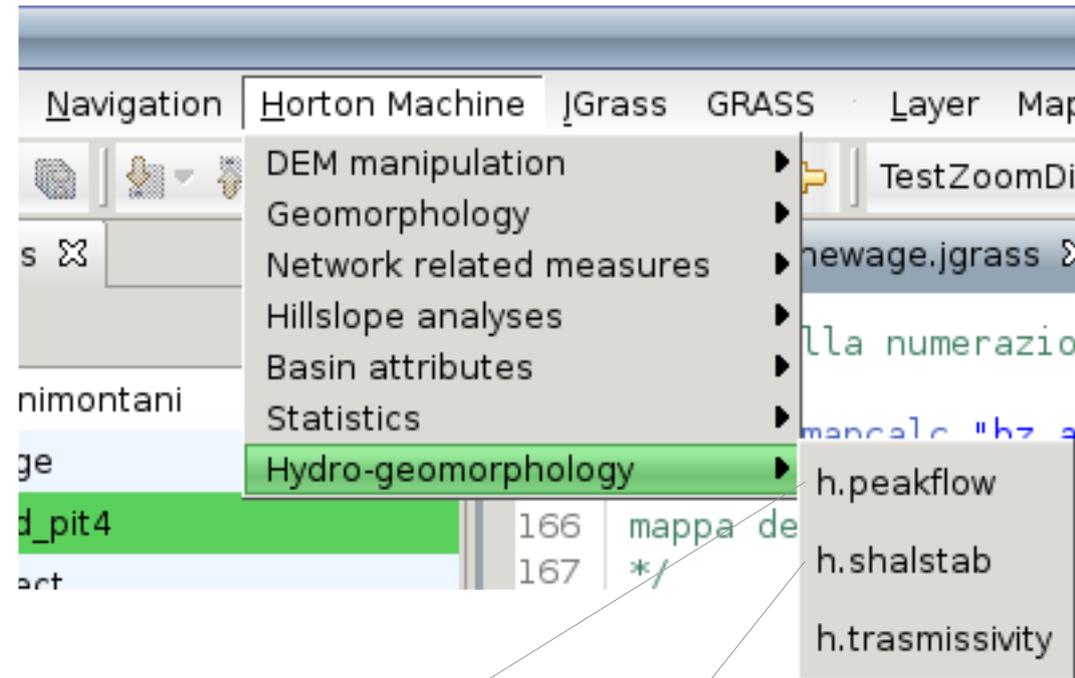
sums the values of an assigned quantity from the point till the outlet

the histogram of a set of data contained in a matrix with respect to the set of data contained in another matrix

# HortonMachine:

The commands are divided in 7 categories:

- DEM manipulation
- Geomorphology
- Network related measures
- Hillslope analyses
- Basin attributes
- Statistics
- Hydro-geomorphology

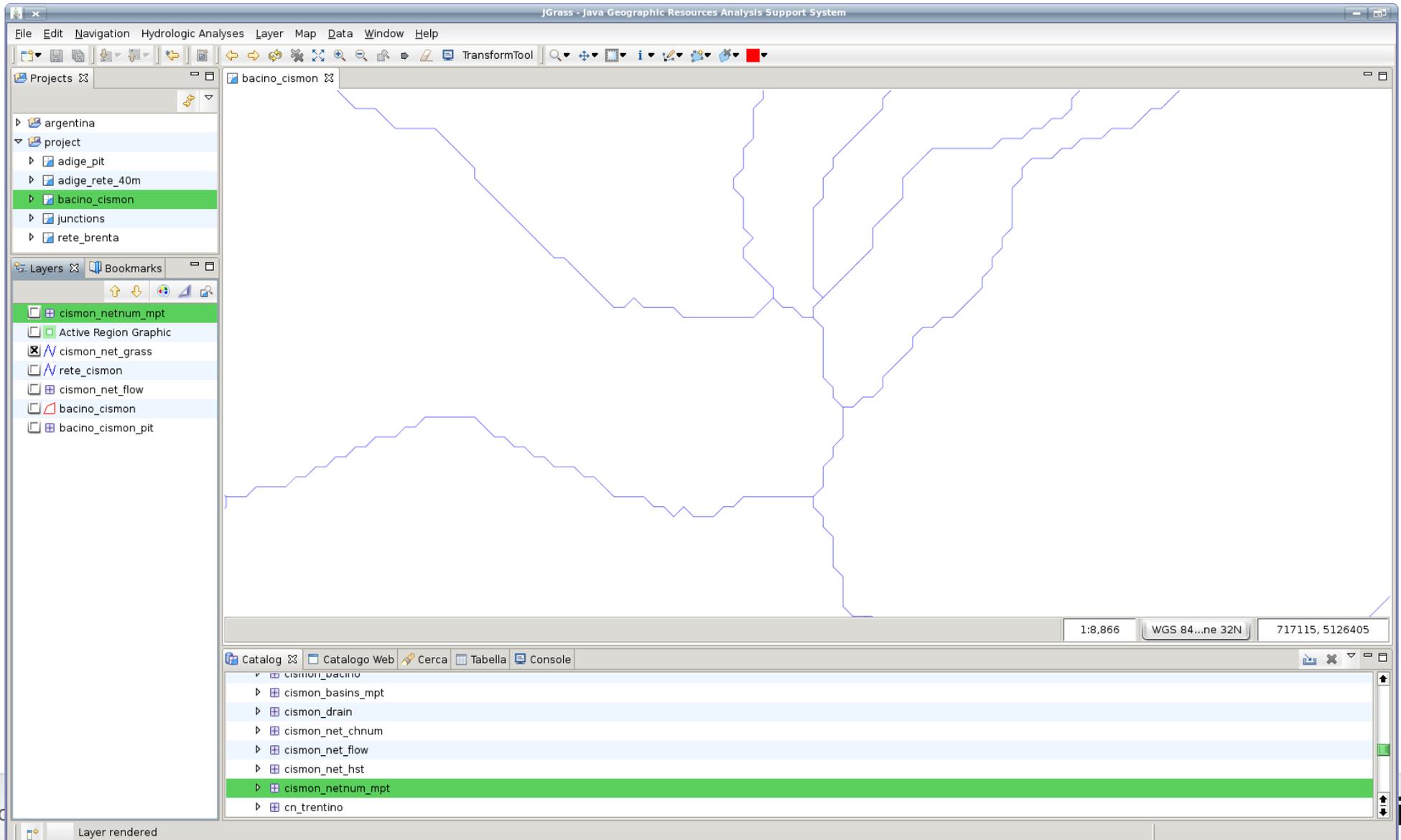


the Peakflow semidistributed model for discharge calculation

the Shalstab hillslope stability model

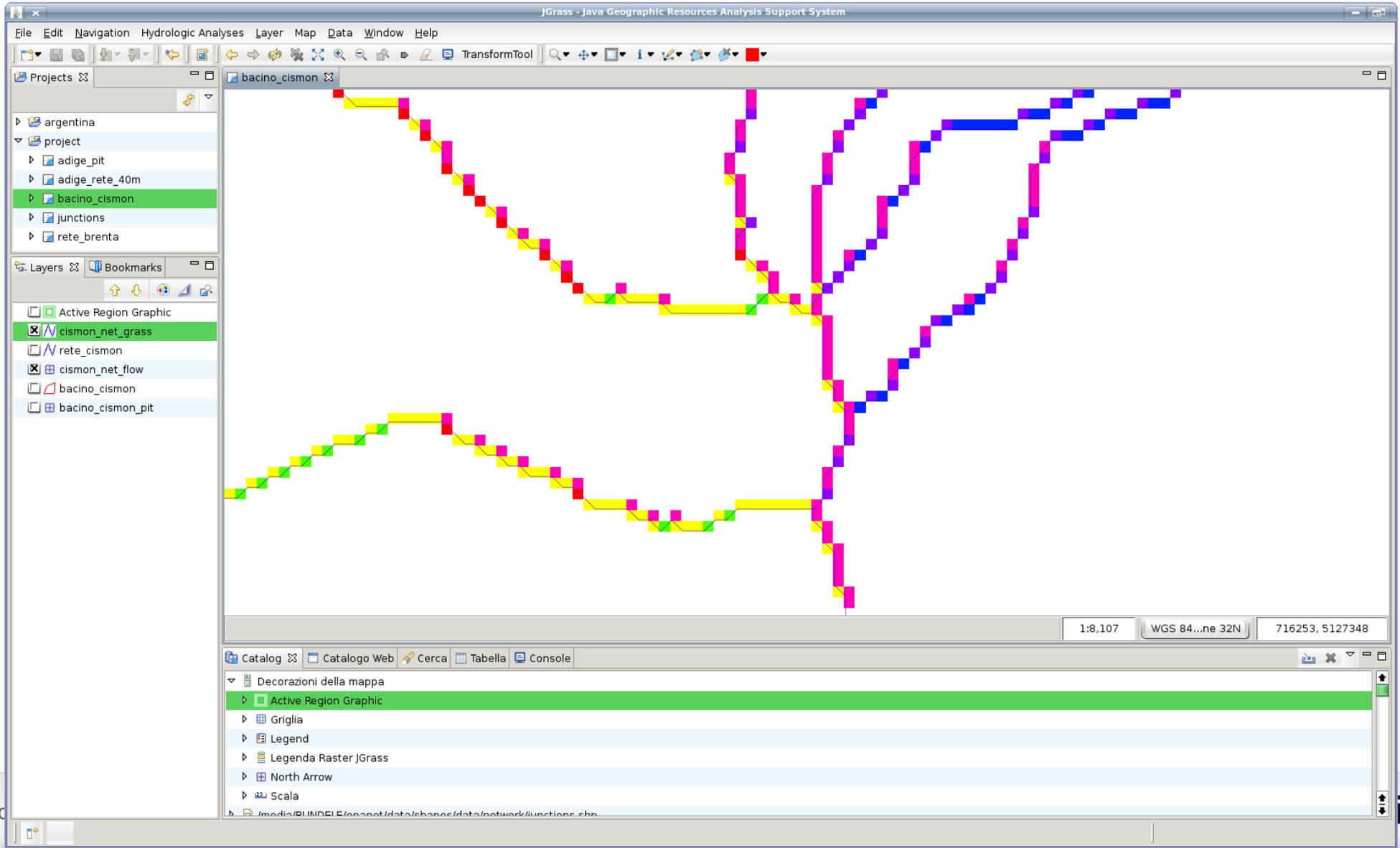
# JGrass and the “Horton machine”

How hard is it to follow a real river network?



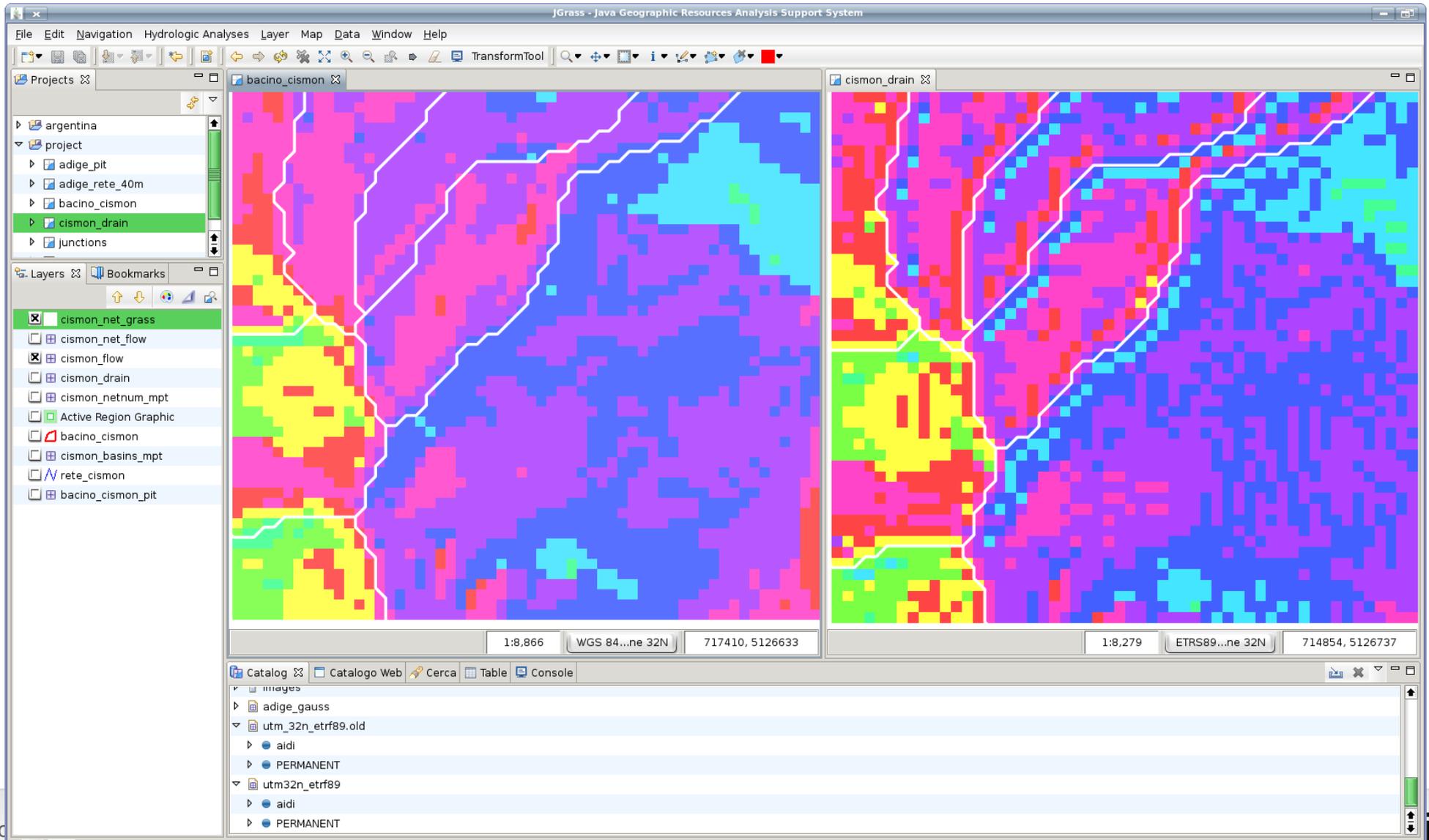
# JGrass and the “Horton machine”

h.netshape2flow: create flowdirections along the network



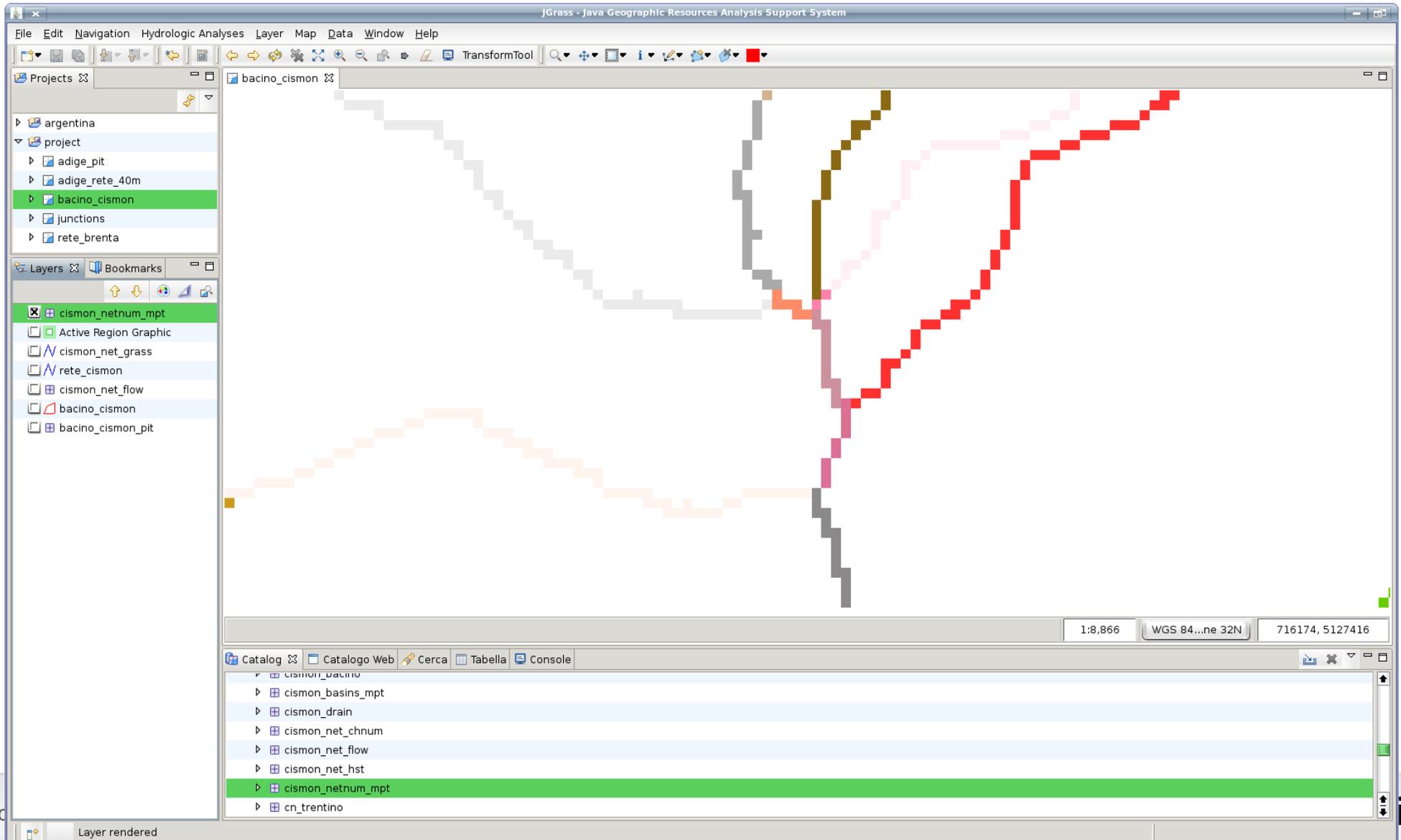
# JGrass and the “Horton machine”

h.draindir: sink flowdirections to follow the real stream



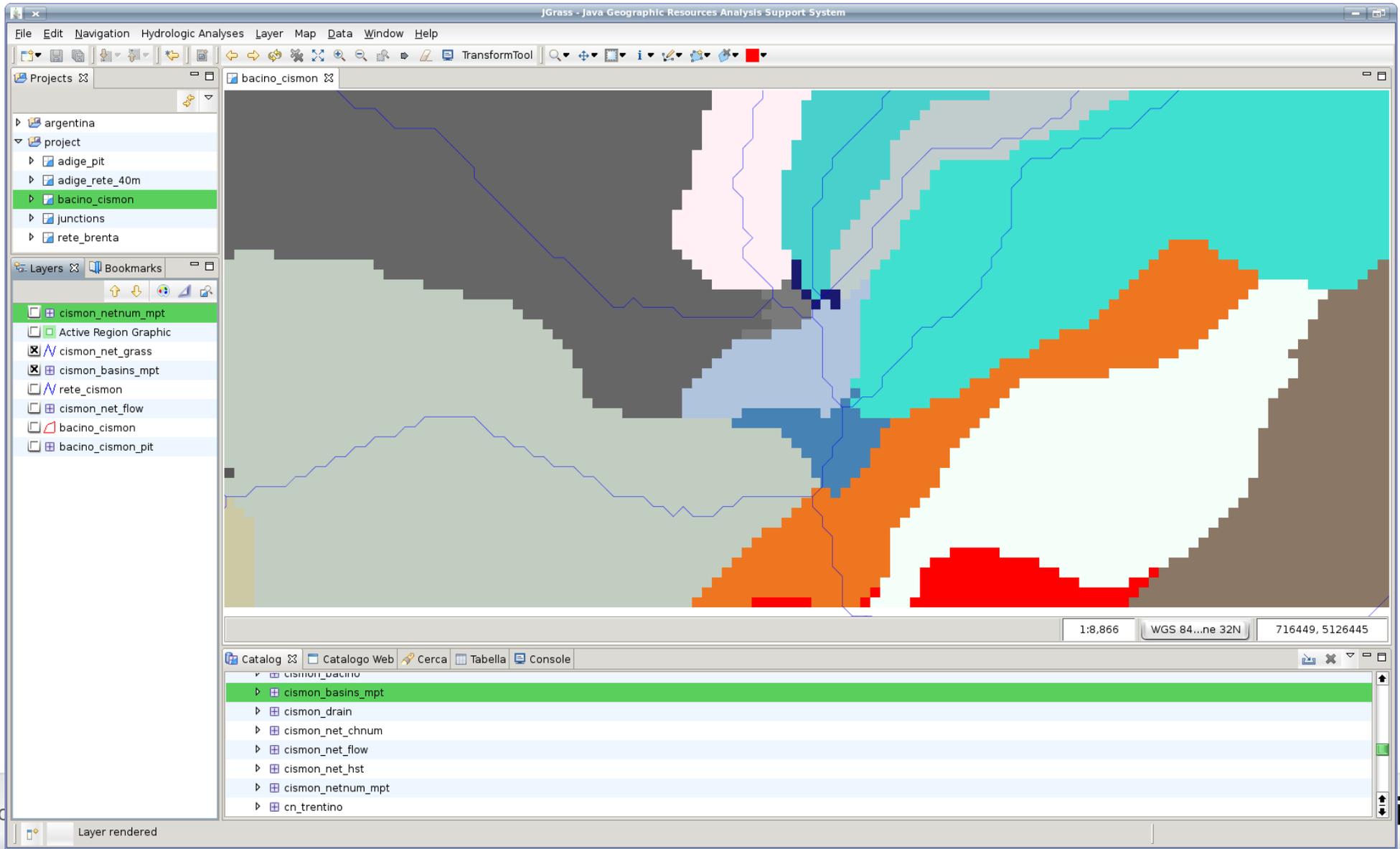
# JGrass and the “Horton machine”

h.netnumbering: numbering of the channels...



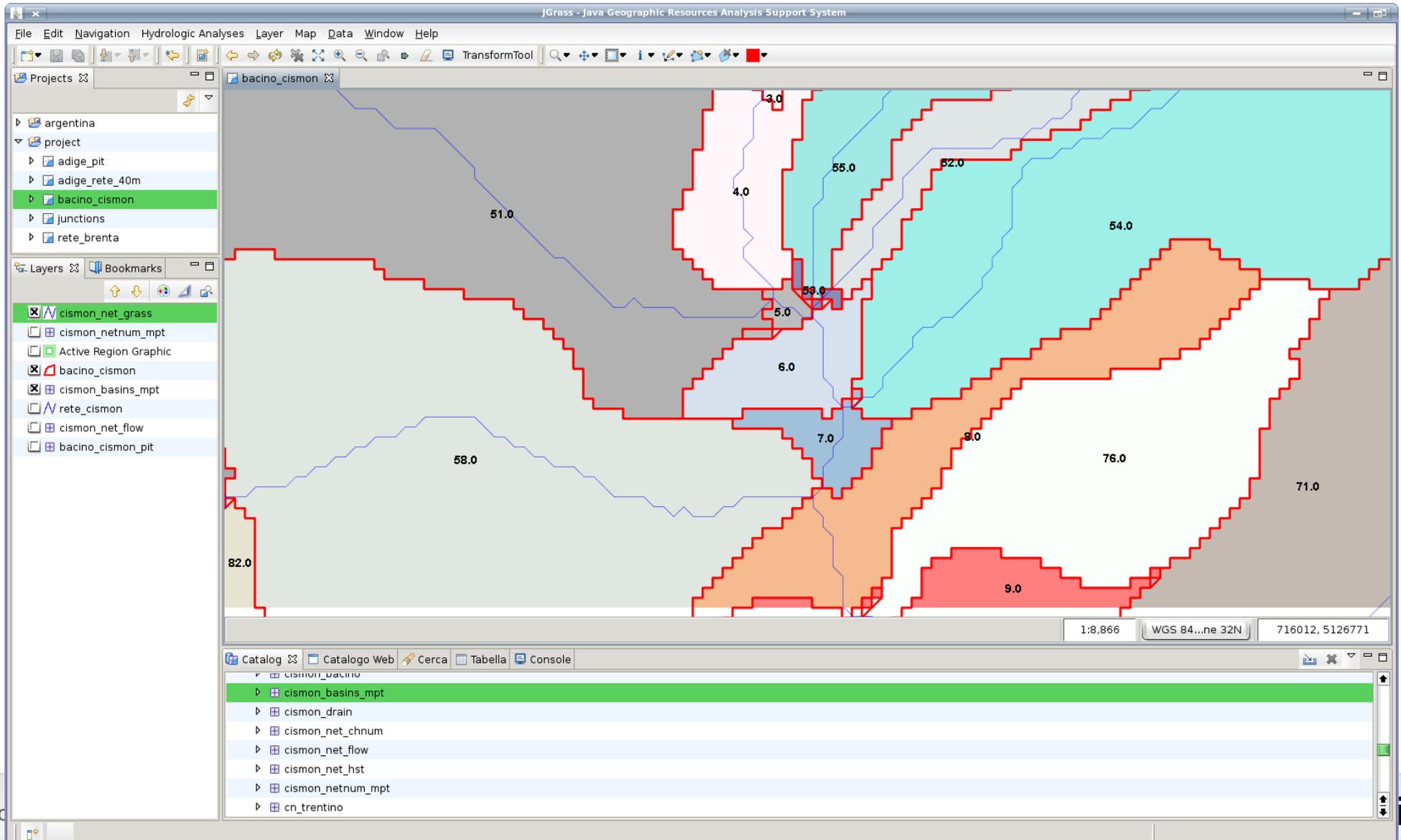
# JGrass and the “Horton machine”

...and creation of the related subbasins



# JGrass and the “Horton machine”

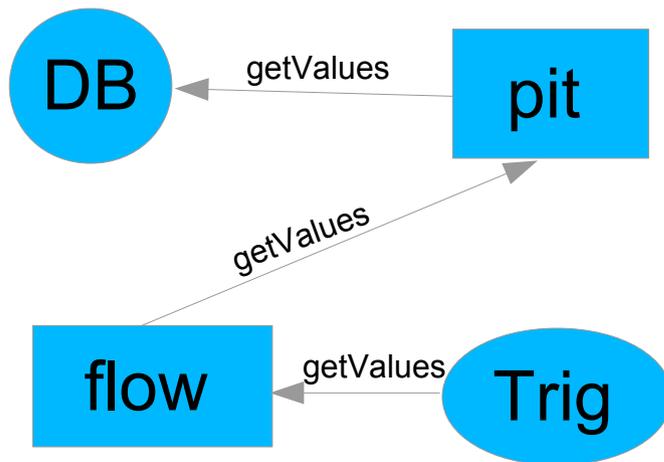
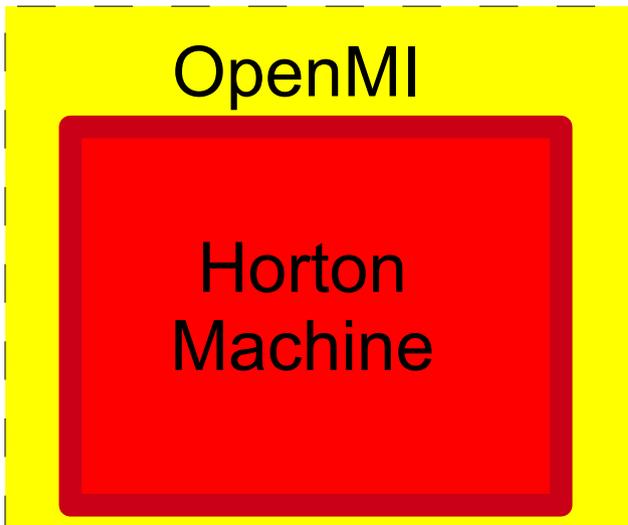
...from which the basin polygons can be extracted to shapefile.



**But again: How is this done?**

# OpenMI

# The HortonMachine - OpenMI Link



- OpenMI is a set of conceptual interfaces to do model linking and execution along a timeline chain
- since it got an international standard and models like Sobek, Hec-ras joined the wave, the effort was done to **adapt ALL the models of the Horton Machine to OpenMI**
- OpenMI is based on a pulling mechanism

# J-Console – the scripting engine

## J-Console Engine

OpenMI

Horton  
Machine

- linking and executing such openmi based models was a bit tricky
- also there was the need to save scenarios, create automatism
- a scripting engine was designed keeping in mind a commandline console and a visual console, a kind of atelier in which to easily play with model components
- a pluggable engine to be able to work also in standalone mode for serverside

# J-Console – the JGrass modeling language

**h.pitfiller --igrass-elevation dtm\_corso --ograss-pit pitmap**

```
def __h_pitfiller_631 = new h_pitfiller( out, err );
Argument[] __argv_637 = new Argument[7];
__argv_637[0] = new Argument( "grassdb", __global_grassdb, true );
__argv_637[1] = new Argument( "location", __global_location, true );
__argv_637[2] = new Argument( "mapset", __global_mapset, true );
__argv_637[3] = new Argument( "time_start_up", __global_startdate, true );
__argv_637[4] = new Argument( "time_ending_up", __global_enddate, true );
__argv_637[5] = new Argument( "time_delta", __global_deltat, true );
__argv_637[6] = new Argument( "remotedburl", __global_remotedb, true );

__h_pitfiller_631.initialize( __argv_637 );
InputGrassRasterMap __igrass_elevation_633 = new InputGrassRasterMap( out, err );
Argument[] __argv_638 = new Argument[9];
__argv_638[0] = new Argument( "igrass", "dtm_corso", true );
__argv_638[1] = new Argument( "quantityid", "elevation", true );
__argv_638[2] = new Argument( "grassdb", __global_grassdb, true );
__argv_638[3] = new Argument( "location", __global_location, true );
__argv_638[4] = new Argument( "mapset", __global_mapset, true );
__argv_638[5] = new Argument( "time_start_up", __global_startdate, true );
__argv_638[6] = new Argument( "time_ending_up", __global_enddate, true );
__argv_638[7] = new Argument( "time_delta", __global_deltat, true );
__argv_638[8] = new Argument( "remotedburl", __global_remotedb, true );

__igrass_elevation_633.initialize( __argv_638 );
Link __igrass_link_elevation_634 = new Link( null, "elevation" );
__igrass_link_elevation_634.connect(
    __igrass_elevation_633
    , __igrass_elevation_633.getOutputExchangeItem( 0 )
    , __h_pitfiller_631
    , __h_pitfiller_631.getInputExchangeItem( 0 )
);
```

generated code

);

if ( false == \_\_igrass\_link\_elevation\_634.isCreated() )

throw new RuntimeException( "Link " + \_\_igrass\_link\_elevation\_634.getID() + " not created." );

# J-Console – the power of scripting

```
String bacino = "riosorna"  
String bacinopit = bacino + "_pit"  
String bacinodtm = bacino + "_dtm"  
String bacinodrain = bacino + "_drain"  
String bacinoflow = bacino + "_flow"  
String bacinotca = bacino + "_tca"  
String bacinoextract = "my" + bacino + "_pit"
```

```
jgrass h.pitfiller --igrass-elevation $bacinodtm --ograss-pit $bacinopit
```

```
jgrass h.flow --igrass-pit $bacinopit --ograss-flow $bacinoflow
```

```
jgrass h.draindir --mode 1 --igrass-pit $bacinopit --igrass-flow $bacinoflow  
--lambda 1 --ograss-dir $bacinodrain --ograss-tca $bacinotca
```

```
jgrass h.wateroutlet --igrass-map $bacinopit --igrass-flow $bacinodrain  
--ograss-basin $bacino --ograss-trim $bacinoextract --north 5075367.33 --east  
656292.04
```

# The abstraction on IO – forcing “clean” models

--oscalar-out xxxxxx

The screenshot shows the uDig application interface. The main window displays a GRASS GIS script in a text editor. The script includes the following content:

```
# LANGUAGE = GROOVY
# STARTDATE =
# ENDDATE =
// date would be there until 2007-08-31 16:30
# DELTAT=
//# MAPSET= /home/moovida/data/hydrocareworkspace/grassdb/utm32n_etrif89/aidi
# MAPSET= /home/moovida/grass/grassdb/flangitest/prova
//# MAPSET = /home/moovida/data/bolzano/utm_newage/newage
# GISBASE= /usr/local/grass-6.3.0RCS/
# RT= /home/moovida/rcpdevelopment/WORKSPACES/eclipseGanimed
# DEBUG= true
# NATIVEDEBUG= false
# TRACE= true
//# NATIVELIBS = /home/moovida/rcpdevelopment/WORKSPACES/ecl

jgrass {
  h.cb
  --igrass-map1 dtm
  --igrass-map2 dtm
  --oscalar-out1 "/home/moovida/TMP/cb.txt"
  --oscalar-out2 "CONSOLE"
  --firstmoment 1
  --lastmoment 2
  --numbins 100
}
```

The console window at the bottom shows the output of the script, displaying a table of elevation data:

```
default.igrass
Creating output 2:
849.6481689453125 5.0
862.814947666266 39.0
872.01180908220313 50.0
886.0863812420819 37.0
899.5408325195312 41.0
912.106231134588 55.0
925.9139291514521 92.0
938.7872198807565 95.0
952.2054201901614 182.0
965.5145106724331 280.0
978.361825783619 371.0
991.5942907350135 569.0
1004.59075006449 583.0
```

The console window also shows a table of elevation data with 29 rows and 4 columns:

5	41.0	899.5408325195312	899.5408325195312	12.463533696602
6	55.0	912.106231134588	912.106231134588	13.792099132444
7	92.0	925.9139291514521	925.9139291514521	12.80683532652
8	95.0	938.7872198807565	938.7872198807565	13.296684203785
9	182.0	952.2054201901614	952.2054201901614	14.716682771453
10	280.0	965.5145106724331	965.5145106724331	14.114723293110
11	371.0	978.361825783619	978.361825783619	14.563877258799
12	569.0	991.5942907350135	991.5942907350135	14.362912500160
13	583.0	1004.59075006449	1004.59075006449	14.040272791055
14	572.0	1017.7794874498061	1017.7794874498061	14.471395142609
15	619.0	1030.9869913276832	1030.9869913276832	14.771784127689
16	628.0	1043.9984360227159	1043.9984360227159	14.349811778170
17	697.0	1057.383601666181	1057.383601666181	14.556635341839
18	775.0	1070.388554750505	1070.388554750505	14.092748681316
19	779.0	1083.568600381599	1083.568600381599	14.426148106111
20	787.0	1096.8471003414866	1096.8471003414866	14.264756903750
21	791.0	1109.9288348597008	1109.9288348597008	14.494723645737
22	832.0	1123.2084514911357	1123.2084514911357	14.422171975253
23	850.0	1136.4002350930607	1136.4002350930607	14.792643955210
24	894.0	1149.5409287830328	1149.5409287830328	14.390153010142
25	924.0	1162.6947479908602	1162.6947479908602	14.611431781901
26	939.0	1175.8126493703824	1175.8126493703824	14.506432165624
27	979.0	1188.9203070386316	1188.9203070386316	14.187165434006
28	1046.0	1202.0161947392596	1202.0161947392596	15.029243619879
29	1133.0	1215.411507965923	1215.411507965923	15.042739890050

# The abstraction on IO – forcing “clean” models

--otable-out xxxxxx

The screenshot displays the uDig GIS application interface. The main window shows a GRASS GIS script in the editor. The script includes the following code:

```
#!/usr/bin/env python
# -*- coding: utf-8 -*-
# Mapset and location
MAPSET = /home/moovida/data/bolzano/utm_newage/newage
# GISBASE
GISBASE = /usr/local/grass-6.3.0RC3/
# RT
RT = /home/moovida/rcpdevelopment/WORKSPACES/eclipseGanimedeTrunk/eu
# DEBUG
DEBUG = true
# NATIVEDEBUG
NATIVEDEBUG = false
# TRACE
TRACE = true
# NATIVELIBS
NATIVELIBS = /home/moovida/rcpdevelopment/WORKSPACES/eclipseGanimedeTrunk/eu

jgrass {
  h.cb
  --igrass-map1 dtm
  --igrass-map2 dtm
  --otable-out1 "UITABLE#bins#meanx#moment 1#moment2"
  --otable-out2 "CONSOLE#bins#meanx#moment 1#moment2"
  --firstmoment 1
  --lastmoment 2
  --numbins 100
}

grass r.colors map=bzadige_net_chnum666 color=rainbow

jgrass {
  h.netshape2flow
  --ishapefile-netshape "/home/moovida/TMP/adige_rete_bz_test.shp"
  --oqrass-flownet bzadige net flo666
}
```

The console window at the bottom shows the output of the script, including the creation of output files and a table of results:

```
default igrass
creating output 1...
Creating output 2...
bins  meanx
849.6481689453125 5.0
862.814947666266 39.0
872.0118090820313 50.0
886.0863812420819 37.0
899.5408325195312 41.0
912.106231134588 55.0
925.9139291514521 92.0
938.7872198807565 95.0
952.2054201901614 182.0
965.5145106724331 280.0
978.361825783619 371.0
```

A separate window displays a table with the following data:

bins	meanx	moment 1	moment2
5.0	849.6481689453125	849.6481689453125	5.395798824145459
39.0	862.814947666266	862.814947666266	8.669853494735435
50.0	872.0118090820313	872.0118090820313	13.243223355850205
37.0	886.0863812420819	886.0863812420819	15.731789925019257
41.0	899.5408325195312	899.5408325195312	12.46353369602099
55.0	912.106231134588	912.106231134588	13.792039132444188
92.0	925.9139291514521	925.9139291514521	12.806835332652554
95.0	938.7872198807565	938.7872198807565	13.296684203785844
182.0	952.2054201901614	952.2054201901614	14.716682771453634
280.0	965.5145106724331	965.5145106724331	14.114723293110728
371.0	978.361825783619	978.361825783619	14.563877258799039
569.0	991.5942907350135	991.5942907350135	14.362912500160746
583.0	1004.59075006449	1004.59075006449	14.040272791055031
572.0	1017.7794874498061	1017.7794874498061	14.471395142609254
619.0	1030.9869913276832	1030.9869913276832	14.771784127689898
628.0	1043.9984360227159	1043.9984360227159	14.349811778170988
697.0	1057.383601666181	1057.383601666181	14.556635341839865
775.0	1070.388554750505	1070.388554750505	14.092748681316152
779.0	1083.568600381599	1083.568600381599	14.426148106112124
787.0	1096.8471003414866	1096.8471003414866	14.264756903750822
791.0	1109.9288348597008	1109.9288348597008	14.494723645737395
832.0	1123.2084514911357	1123.2084514911357	14.42217197525315
850.0	1136.4002350930607	1136.4002350930607	14.792643955210224
894.0	1149.5409287830328	1149.5409287830328	14.390153010142967
924.0	1162.6947479908602	1162.6947479908602	14.611431781901047



# The abstraction on IO – forcing “clean” models

The same applies for GIS data, for example:

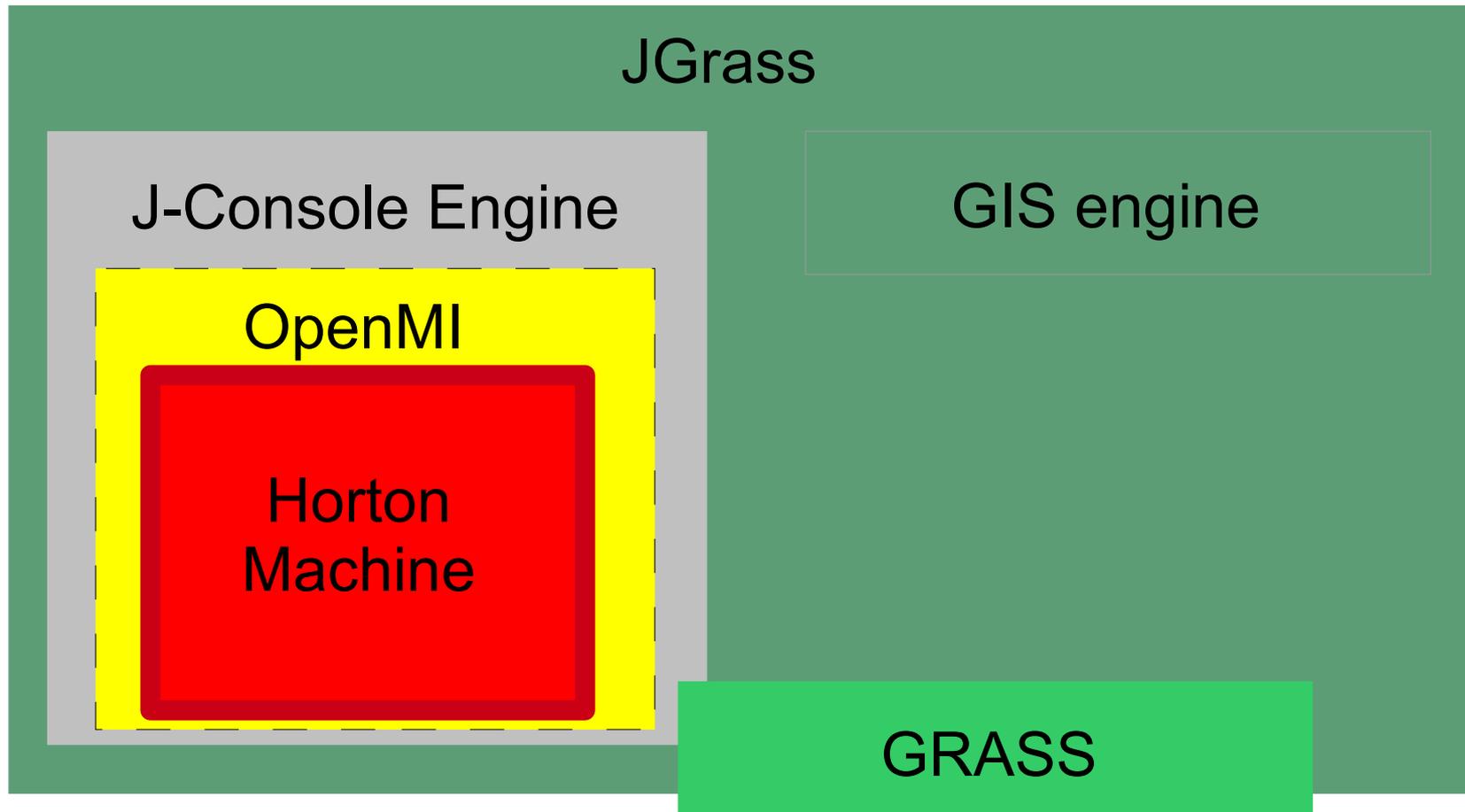
Vector data can be read from shapefiles or from postgis databases.

Raster data can be read from different formats (GRASS, ESRI, TIFF)

**Where does this all take place?**

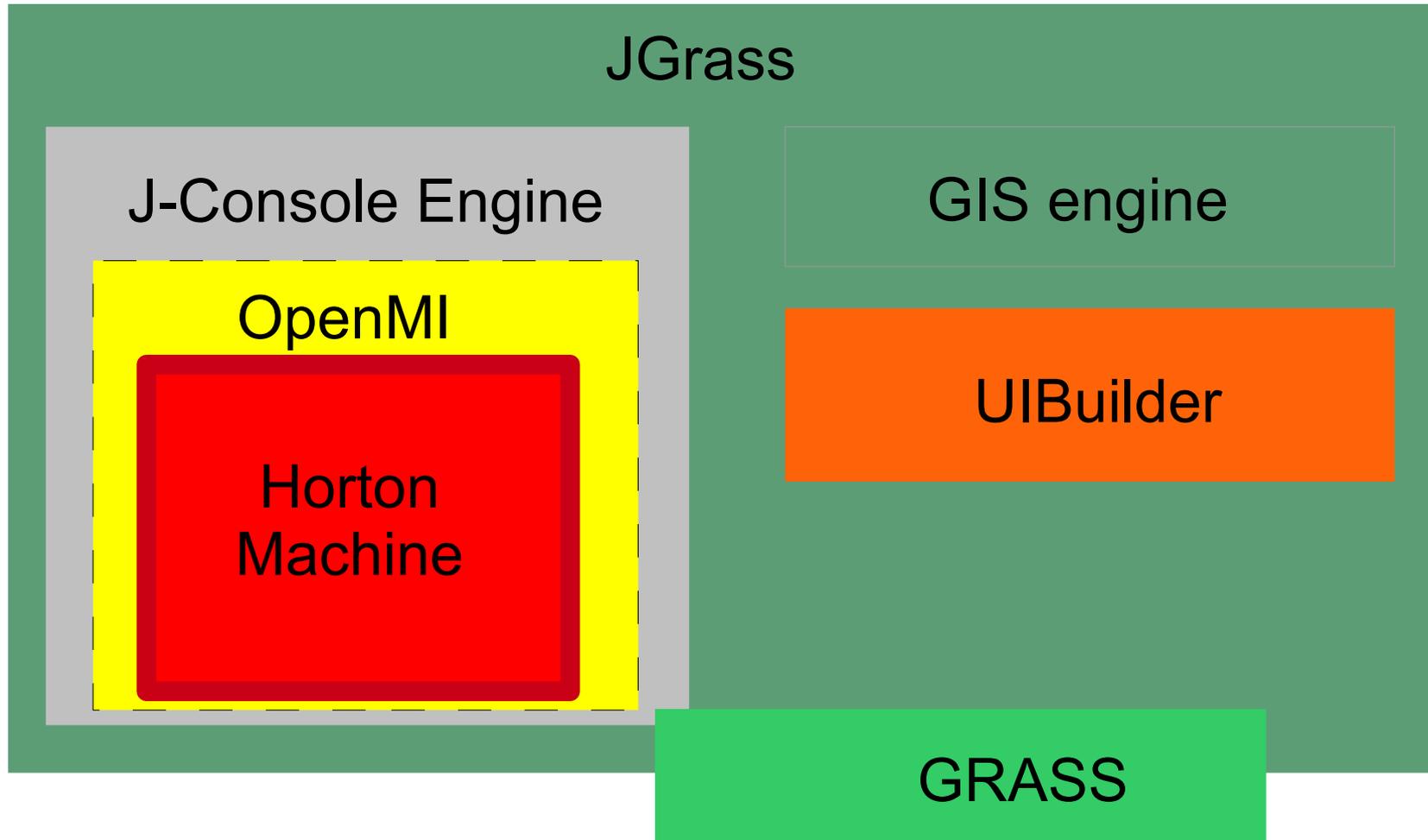
# JGrass

# JGrass



- JGrass supplies the GIS engine, raster analysis tools
- Connection to the GRASS GIS engine

# the UIBuilder – graphical interfaces facilities



- UIBuilder that creates GUI based on XML descriptions

# the UIBuilder – graphical interfaces facilities

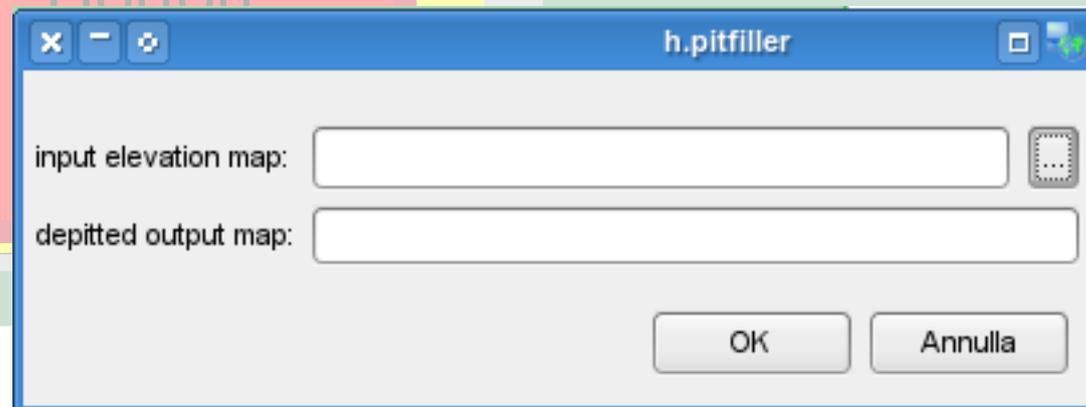
JGrass

Console Engine

GIS engine

```
<command·descr="h.pitfiller"·name="h.pitfiller">¶  
...<field·descr="input·elevation·map"·name="input"·order="0"·repr="--igrass·elevation·#"·required="true"·type="rastermap"/>¶  
...<field·descr="depitted·output·map"·name="output"·order="1"·repr="--ogress·pit·#"·required="true"·type="string"/>¶  
</command>
```

UIBuilder



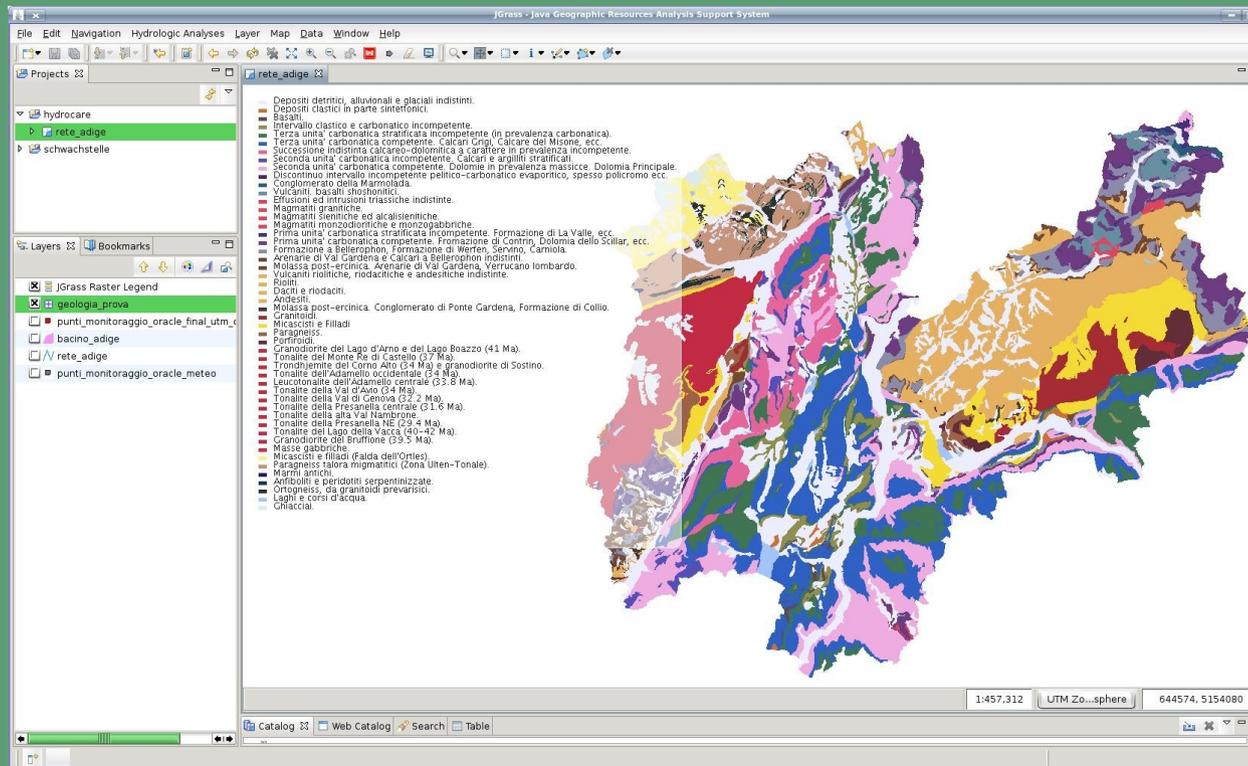
- UIBuilder that creates GUI based on XML descriptions

# JGrass, extending the rcp platform

Eclipse RCP

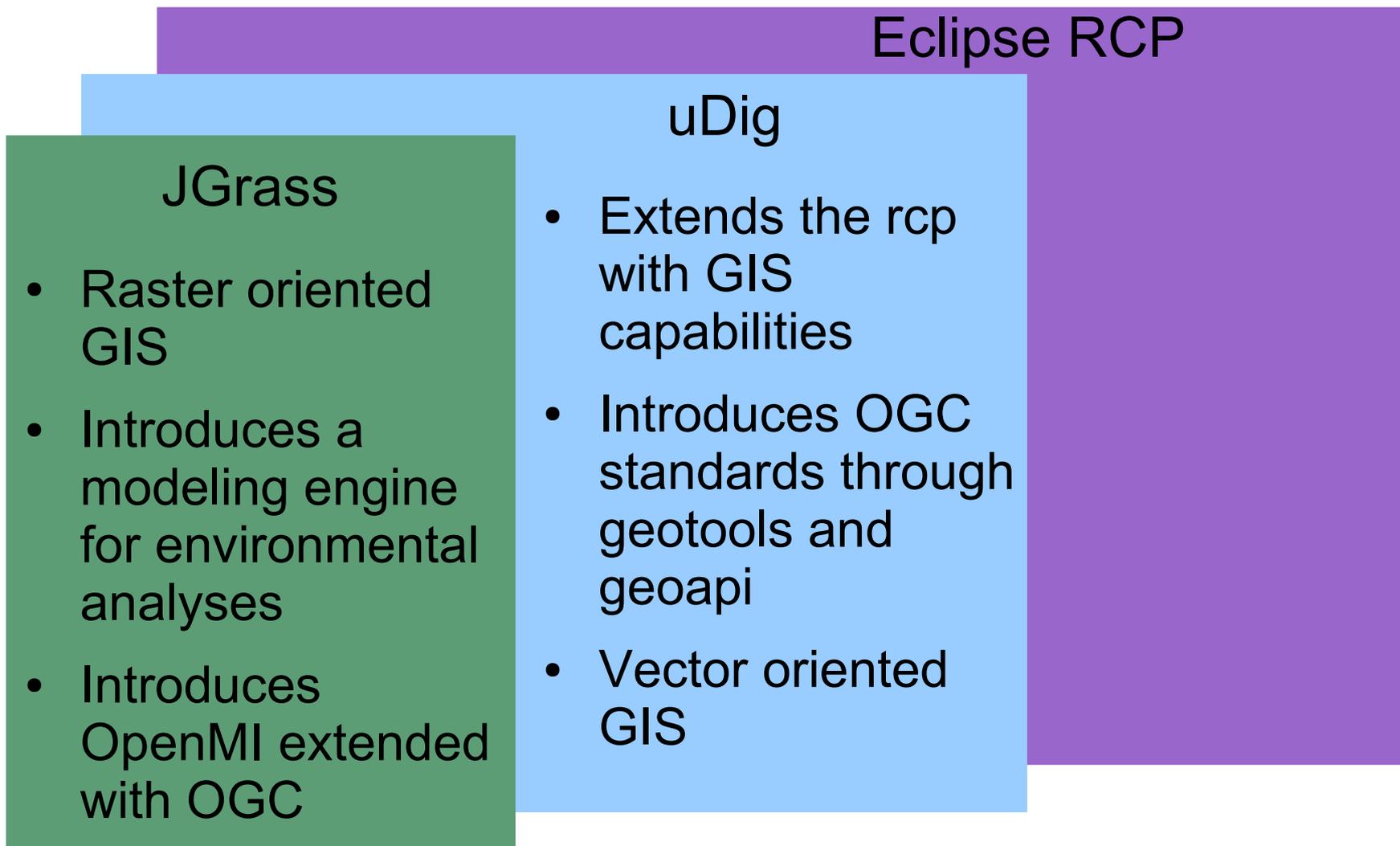
uDig

JGrass



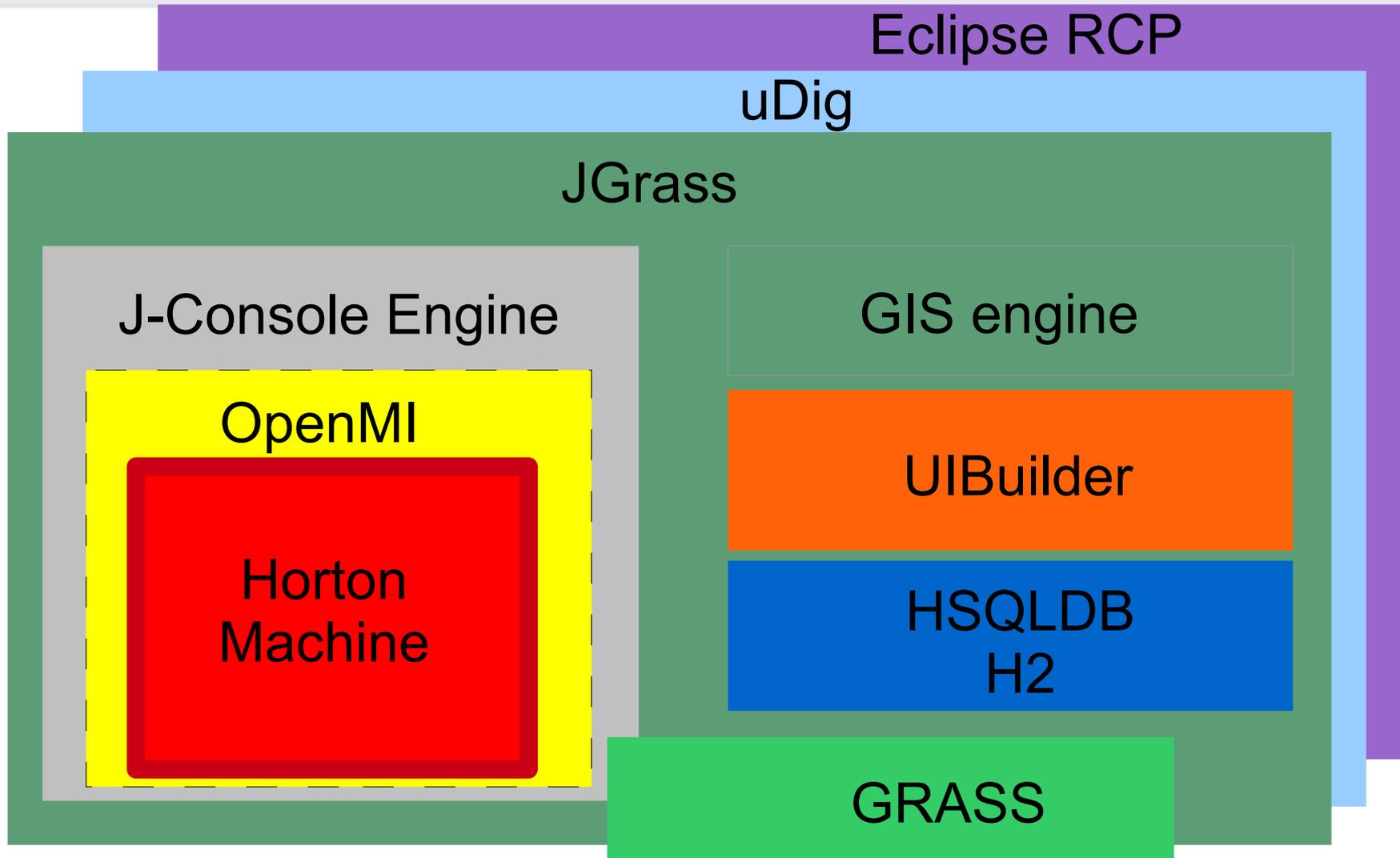
- JGrass is built on top of the uDig GIS-framework
- All is built on top of the Rich-Client-Platform by IBM

# JGrass, extending the rcp platform



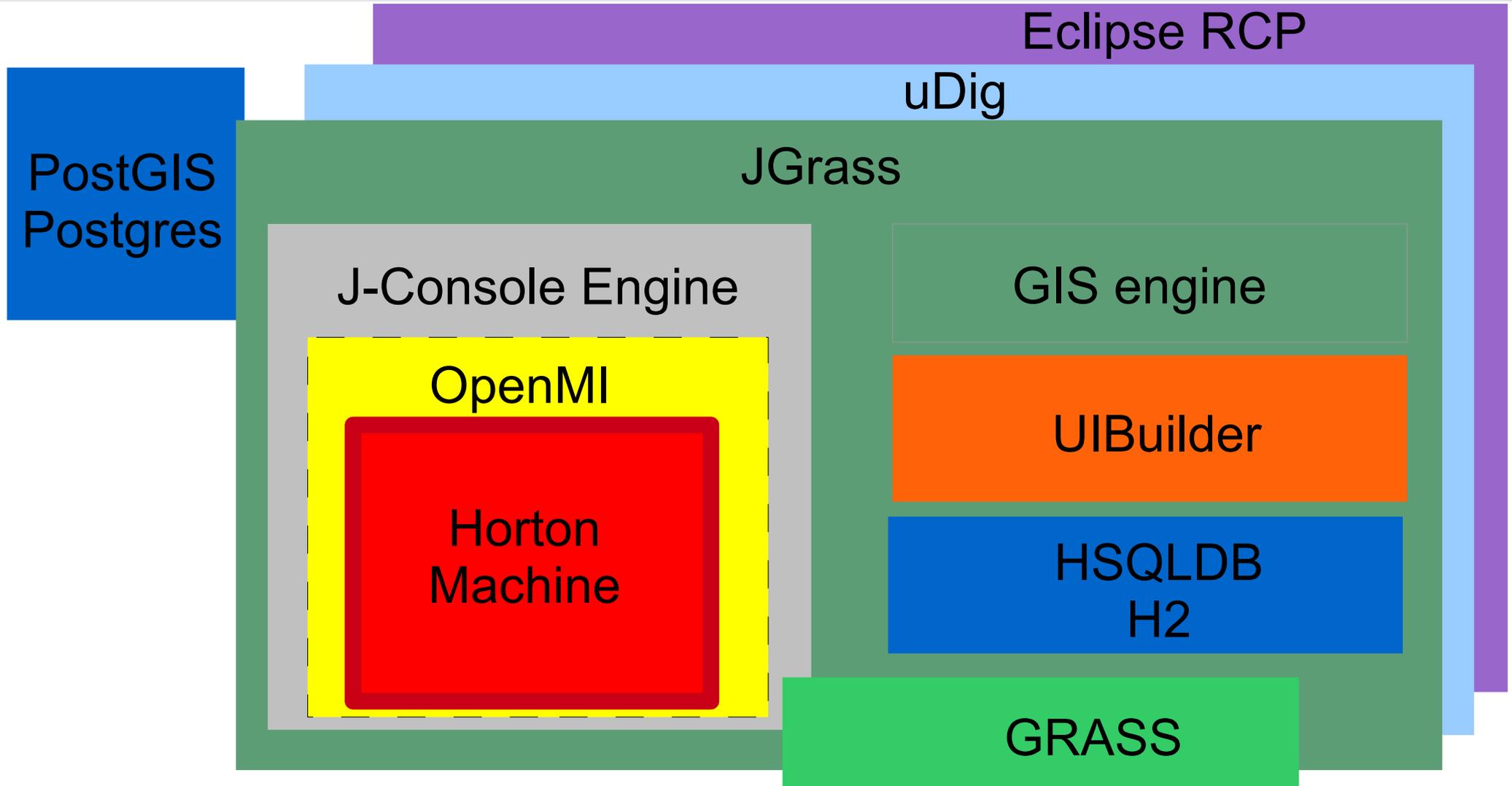
**OGC**

# The database - internal non-spatial H\*DB



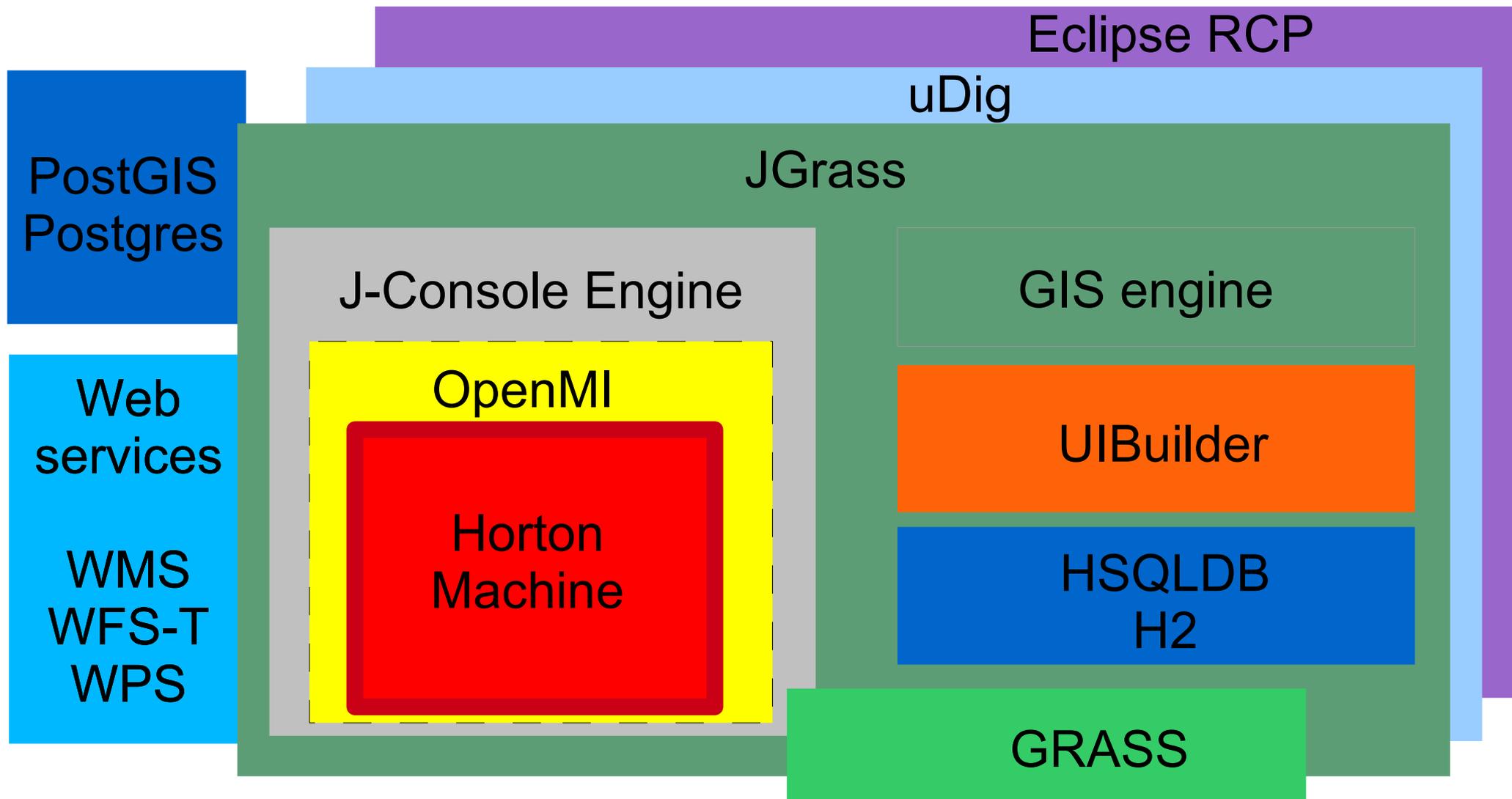
- An internal portable database is shipped with JGrass (non spatial)
- HSQLDB/H2, automatically started at JGrass startup

# The database – central spatial Postgis



- through uDig JGrass exploits the connection to several spatial database types out of the box, as postgis, oracle spatial or arcsde

# Webservices

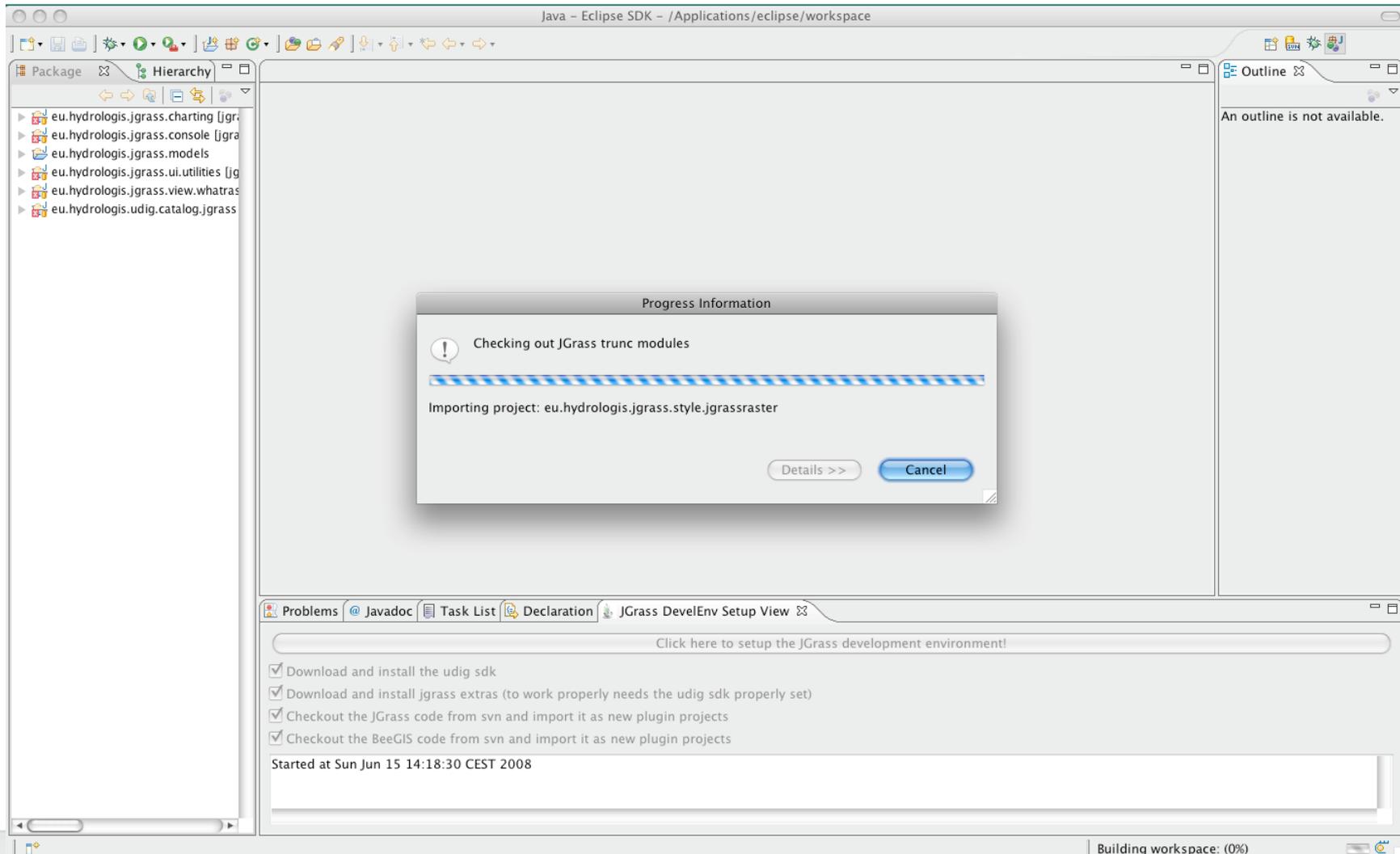


- the uDig link assures support for several web services

# Future development

# Developer tools

An eclipse plugin is in development, which automatically installs all needed tools and development kits, as well as source codes, to get started with JGrass development.

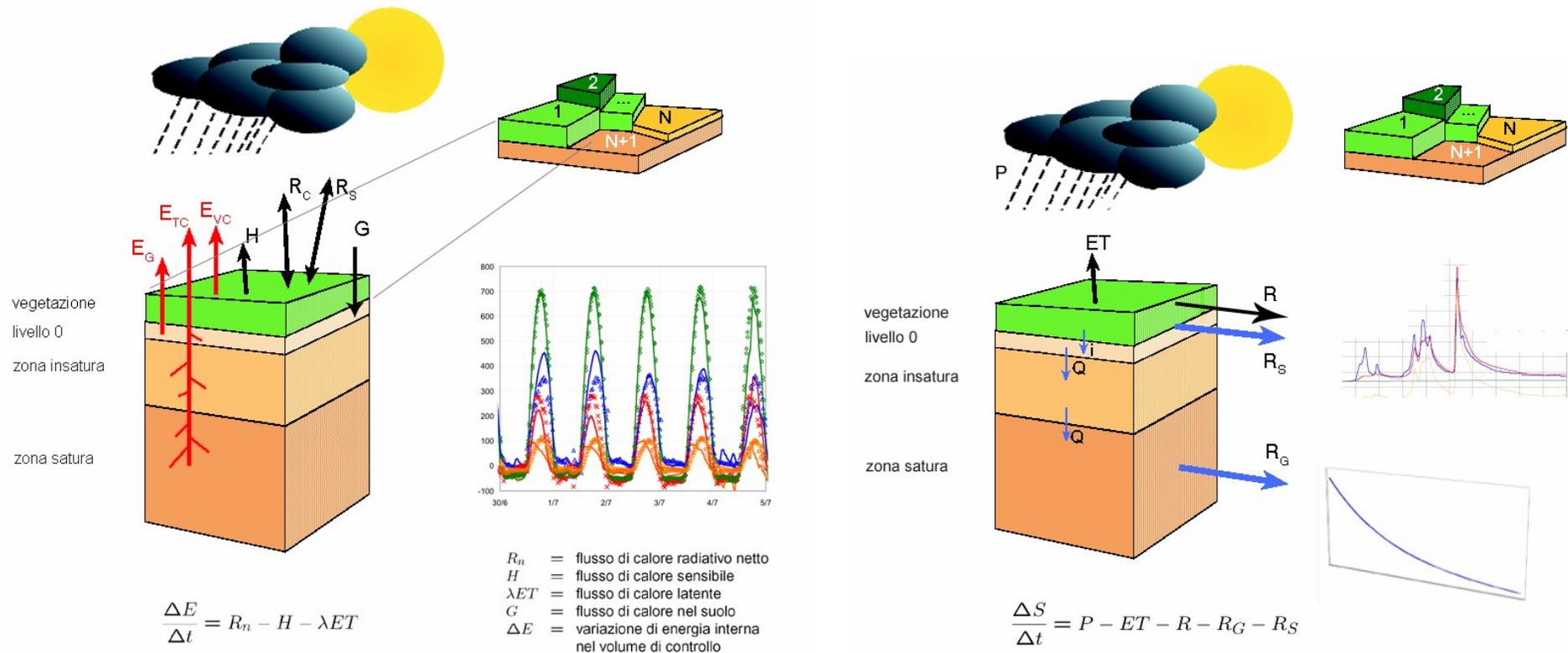


# Integration of geotop into JGrass

GEOtop is a hydrological distributed model which integrates water and energy budgets in complex terrain.

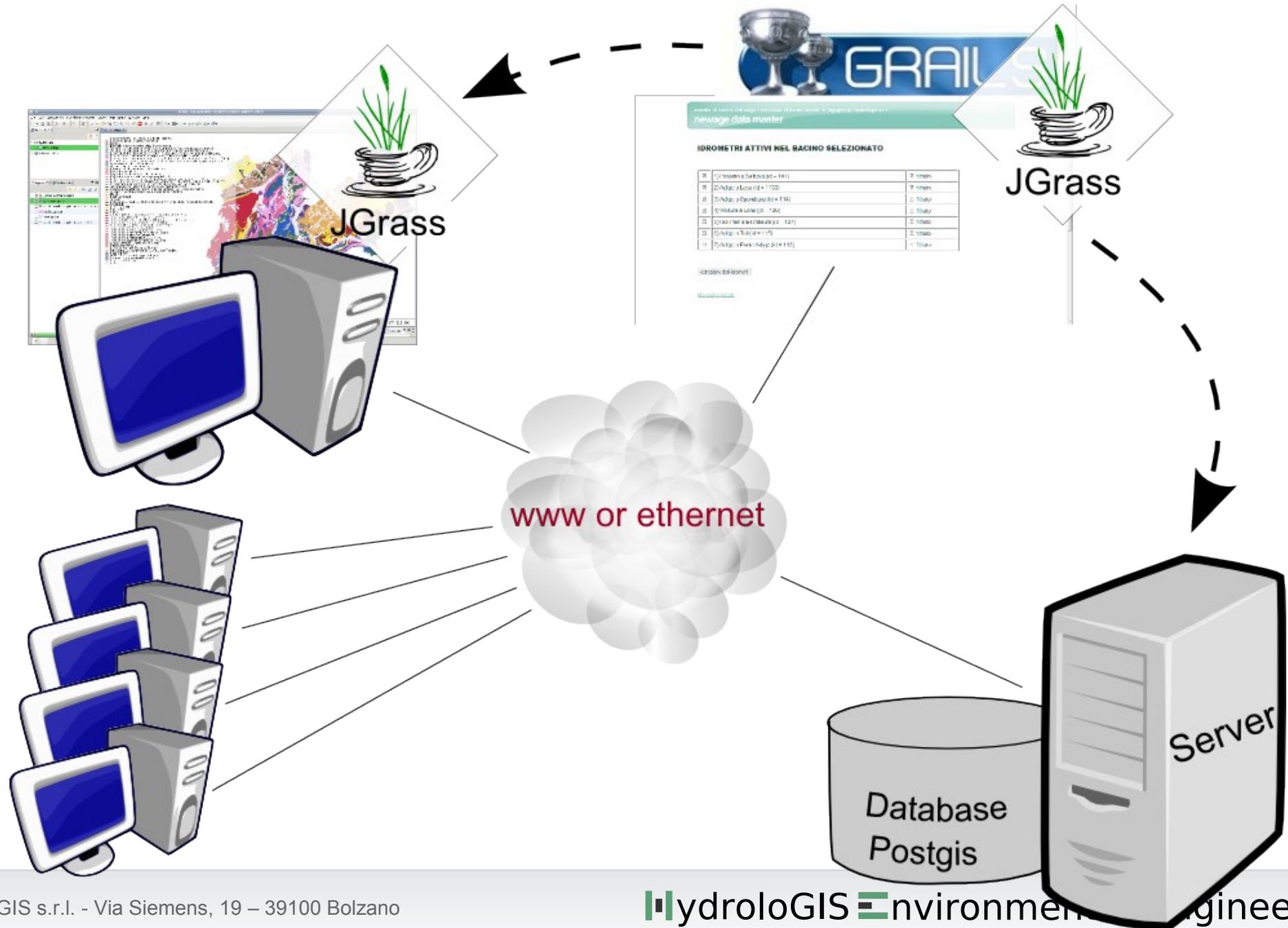
# Integration of geotop into JGrass

Square structured grid based on the DEM



Meteo Data Interpolator - MicroMET  
 Separation - Rainfall – Snow  
 Energy Budget  
 Water Budget

# Further development of JGrass's preferred environment



# JGrass, geowind, NWW

World Wind Airspaces

Layers

- Stars
- Atmosphere
- NASA Blue Marble Image
- BlueMarble (WMS) 05/2004
- i-cubed Landsat
- USGS Urban Area Ortho
- Grass layer
- Airspaces
- Annotations
- Track Pipes
- Place Names
- World Map
- Scale bar
- Compass

Load Demo Airspaces

Zoom to Demo Airspaces

Save Airspaces

Read Airspaces

Vertical Exaggeration

2

1x 2x 4x 8x

Altitude 31 km Lat 46.7128° Lon 10.9551° Elev 2,648 meters

5000 m

Merano



UNIVERSITÀ DEGLI STUDI  
DI TRENTO

CUDAM - Centro Universitario per la Difesa  
Idrogeologica dell'Ambiente Montano

HydroloGIS

Environmental

Engineering

# Environmental modeling within the framework of GIS

[www.jgrass.org](http://www.jgrass.org)  
[www.geotop.org](http://www.geotop.org)